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## *The Director*

*of the United States Patent and Trademark Office has received an application for a patent for a new and useful invention. The title and description of the invention are enclosed. The requirements of law have been complied with, and it has been determined that a patent on the invention shall be granted under the law.*

*Therefore, this United States*

# *Patent*

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*Katherine Kelly Vidal*

DIRECTOR OF THE UNITED STATES PATENT AND TRADEMARK OFFICE

## Maintenance Fee Notice

If the application for this patent was filed on or after December 12, 1980, maintenance fees are due three years and six months, seven years and six months, and eleven years and six months after the date of this grant, or within a grace period of six months thereafter upon payment of a surcharge as provided by law. The amount, number and timing of the maintenance fees required may be changed by law or regulation. Unless payment of the applicable maintenance fee is received in the United States Patent and Trademark Office on or before the date the fee is due or within a grace period of six months thereafter, the patent will expire as of the end of such grace period.

## Patent Term Notice

If the application for this patent was filed on or after June 8, 1995, the term of this patent begins on the date on which this patent issues and ends twenty years from the filing date of the application or, if the application contains a specific reference to an earlier filed application or applications under 35 U.S.C. 120, 121, 365(c), or 386(c), twenty years from the filing date of the earliest such application (“the twenty-year term”), subject to the payment of maintenance fees as provided by 35 U.S.C. 41(b), and any extension as provided by 35 U.S.C. 154(b) or 156 or any disclaimer under 35 U.S.C. 253.

If this application was filed prior to June 8, 1995, the term of this patent begins on the date on which this patent issues and ends on the later of seventeen years from the date of the grant of this patent or the twenty-year term set forth above for patents resulting from applications filed on or after June 8, 1995, subject to the payment of maintenance fees as provided by 35 U.S.C. 41(b) and any extension as provided by 35 U.S.C. 156 or any disclaimer under 35 U.S.C. 253.



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(12) **United States Patent**  
**Brucker et al.**

(10) **Patent No.:** **US 11,744,993 B2**  
(45) **Date of Patent:** **Sep. 5, 2023**

(54) **SYSTEM AND METHOD FOR DEFLECTION MECHANISM WITH EXPANDABLE CONSTRAINT**

(71) Applicant: **Innovations in Medicine, LLC**,  
Minnetonka, MN (US)

(72) Inventors: **Gregory G. Brucker**, Minneapolis, MN  
(US); **Steven D. Savage**, Lake Havasu  
City, AZ (US)

(73) Assignee: **Innovations in Medicine, LLC**,  
Minnetonka, MN (US)

(\*) Notice: Subject to any disclaimer, the term of this  
patent is extended or adjusted under 35  
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19, 2021.

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**A61M 25/01** (2006.01)  
**A61B 90/00** (2016.01)

(52) **U.S. Cl.**  
CPC ..... **A61M 25/0147** (2013.01); **A61B 90/04**  
(2016.02); **A61M 25/0136** (2013.01); **A61B**  
**2090/0427** (2016.02); **A61M 25/0138**  
(2013.01)

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CPC ..... **A61M 25/0147**; **A61M 25/0144**; **A61M**  
**2025/018**; **A61B 90/04**; **A61B 90/0427**  
See application file for complete search history.

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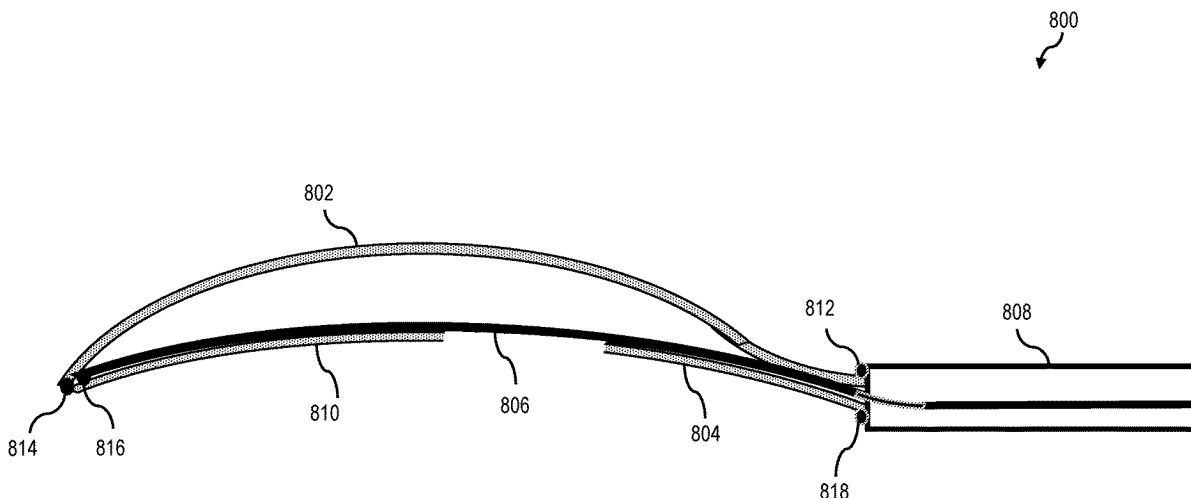
*Primary Examiner* — Carrie R Dorna

(74) *Attorney, Agent, or Firm* — Jonathan M. Rixen;  
Charles A. Lemaire; Lemaire Patent Law Firm, P.L.L.C.

(57) **ABSTRACT**

A deflection system for deflecting a body lumen that includes a deflection mechanism, wherein the deflection mechanism includes: a beam having a proximal end and a distal end, wherein the beam includes a neutral position and a deflected position, a pull wire coupled to the distal end of the beam, wherein the beam is configured to be placed in the deflected position when a tension force is applied to the pull wire, and wherein at least a portion of the pull wire is configured to move to a displacement distance away from the beam when the tension force is applied to the pull wire, and one or more constraint members operatively coupled to the beam, wherein each one of the one or more constraint members is configured to limit the displacement distance of the pull wire from the beam when the tension force is applied to the pull wire.

**18 Claims, 21 Drawing Sheets**



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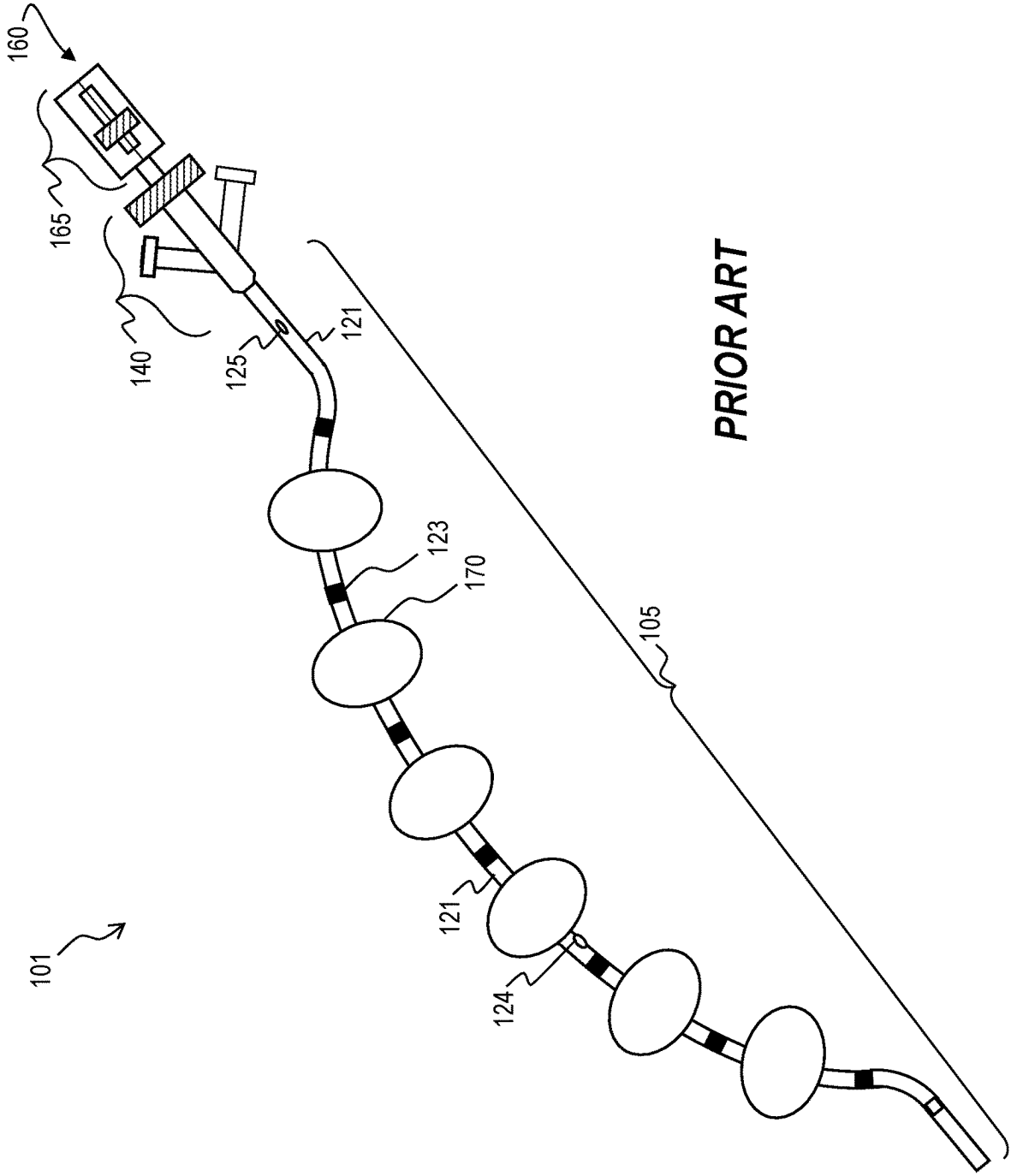
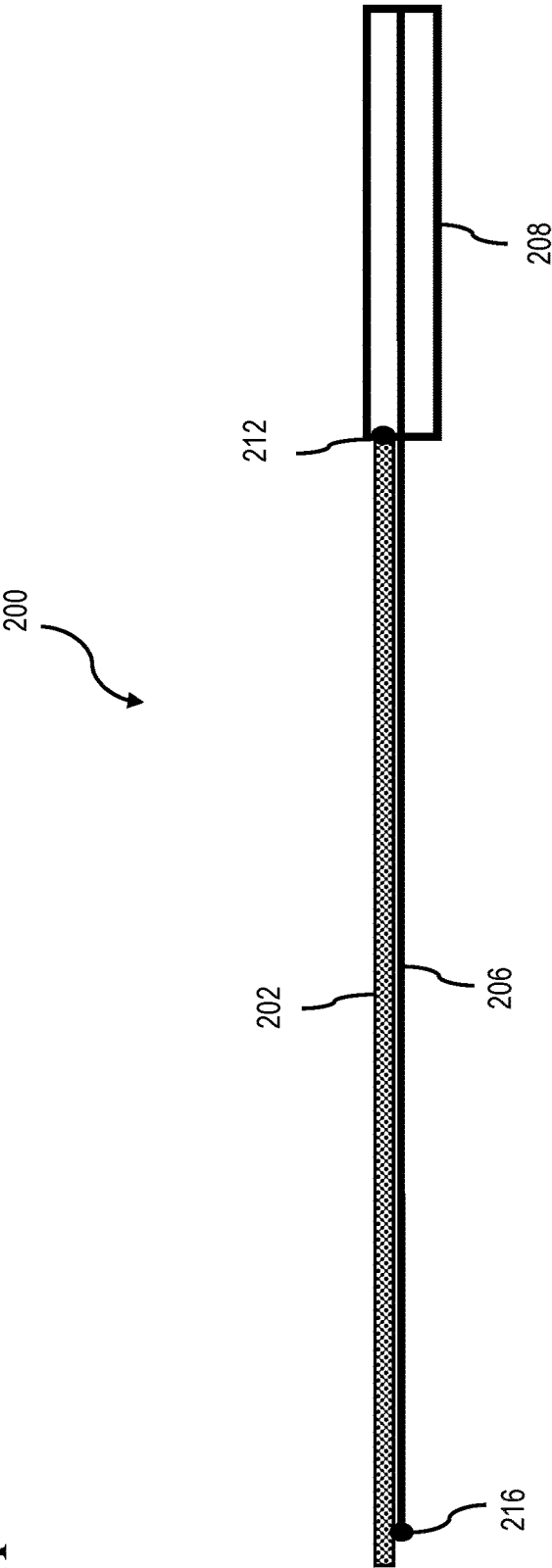


FIG. 1

FIG. 2A



PRIOR ART

FIG. 2B

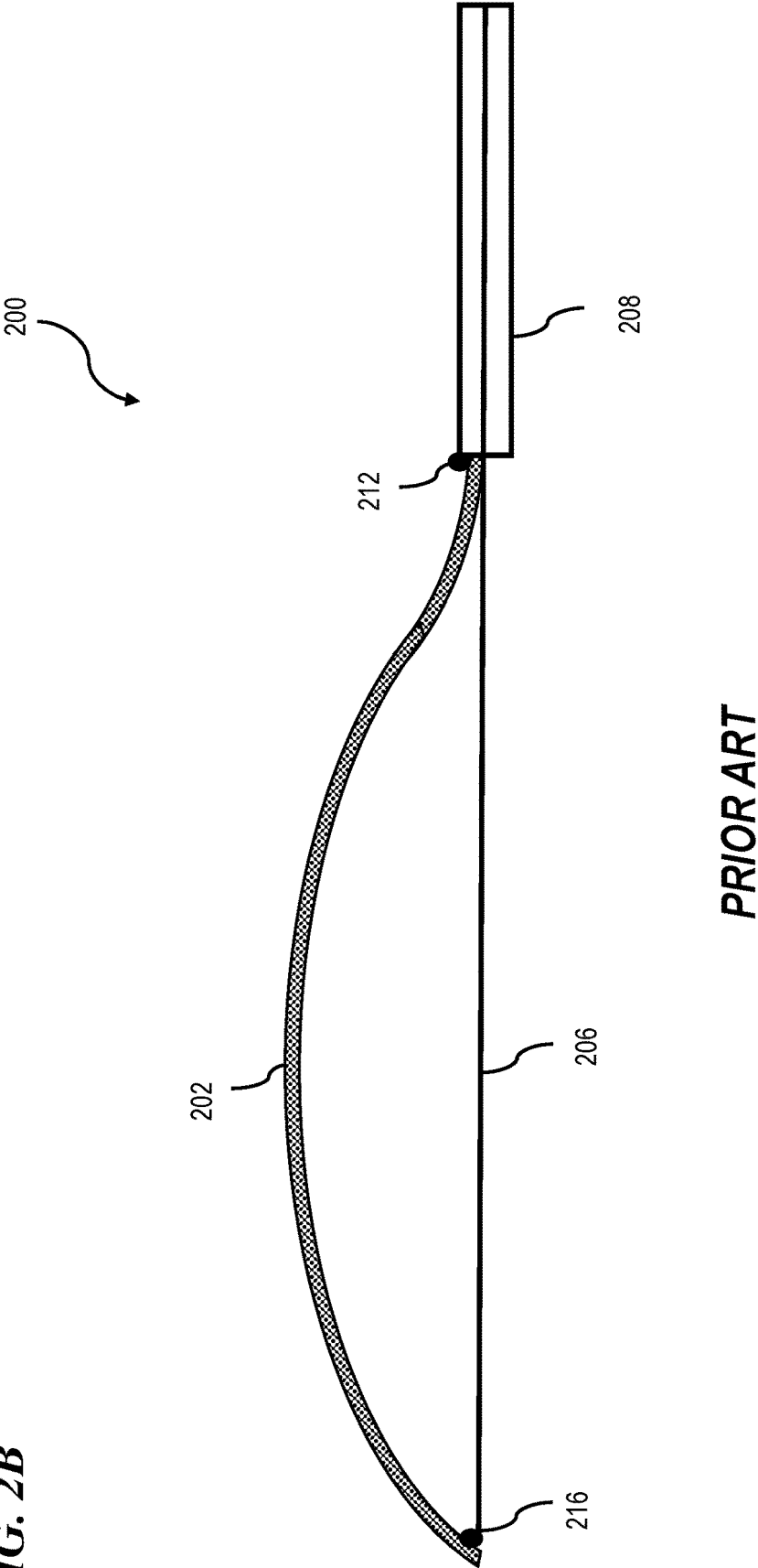
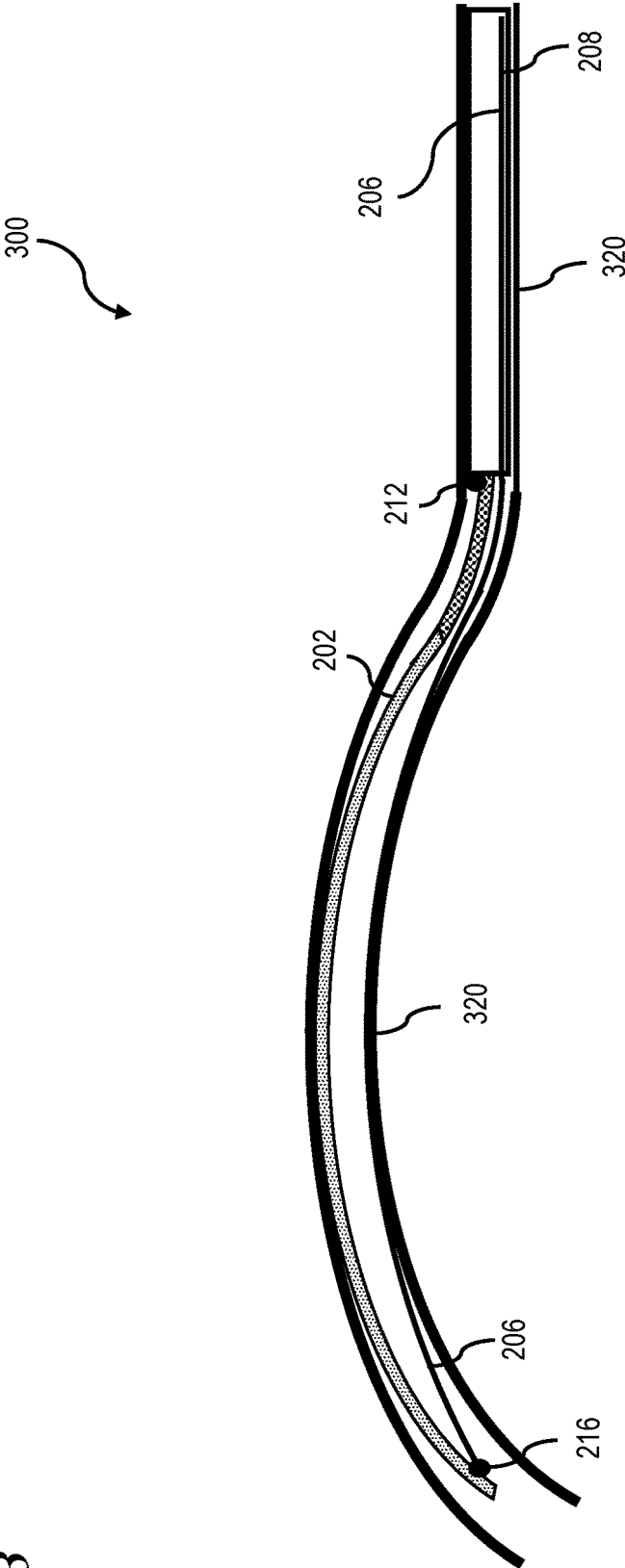


FIG. 3



PRIOR ART



FIG. 4A

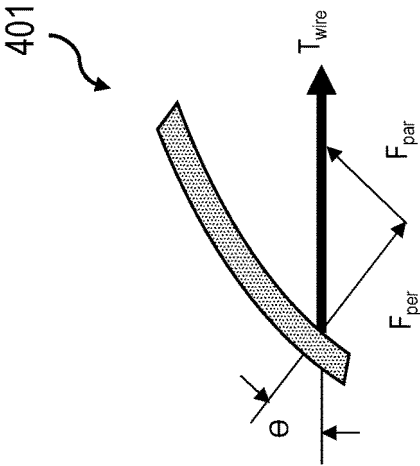


FIG. 4B

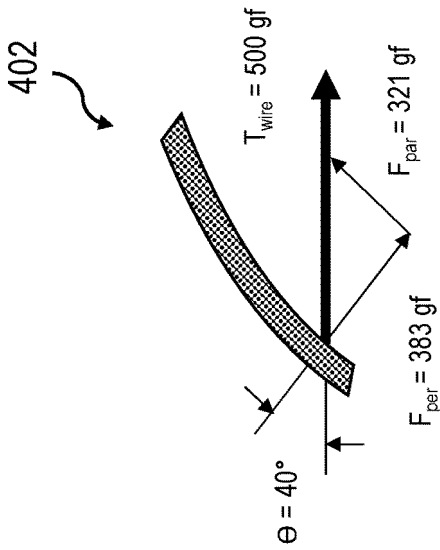


FIG. 4C

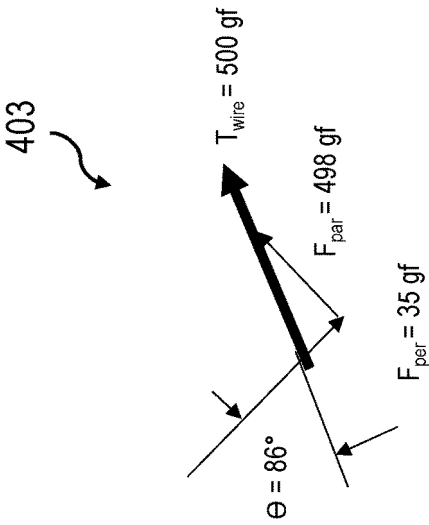
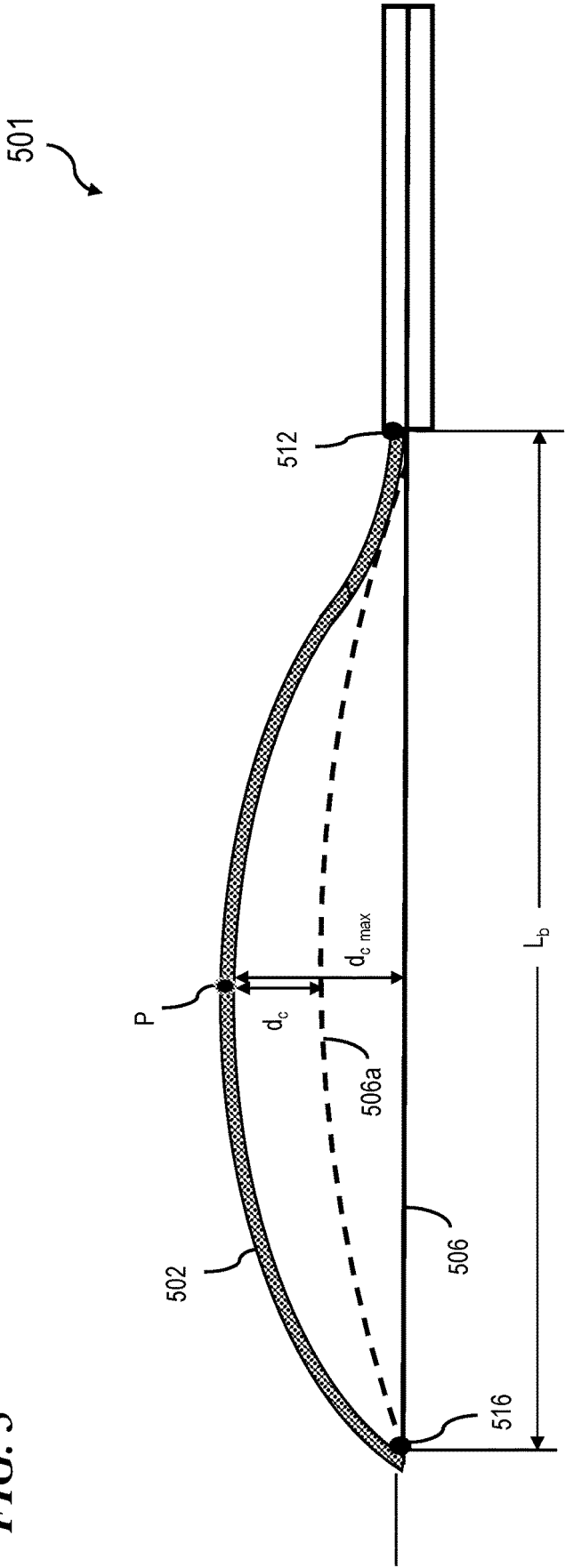


FIG. 5



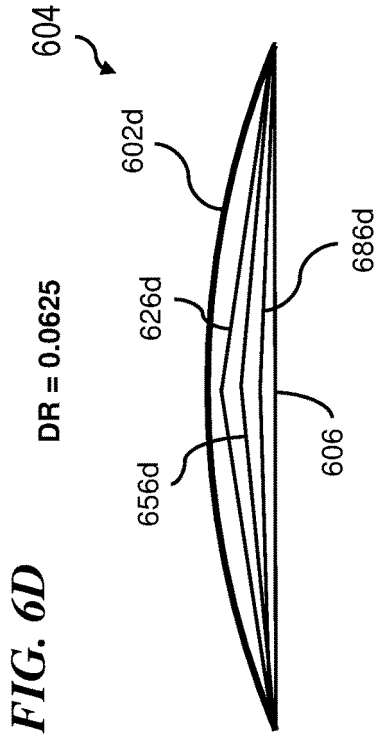
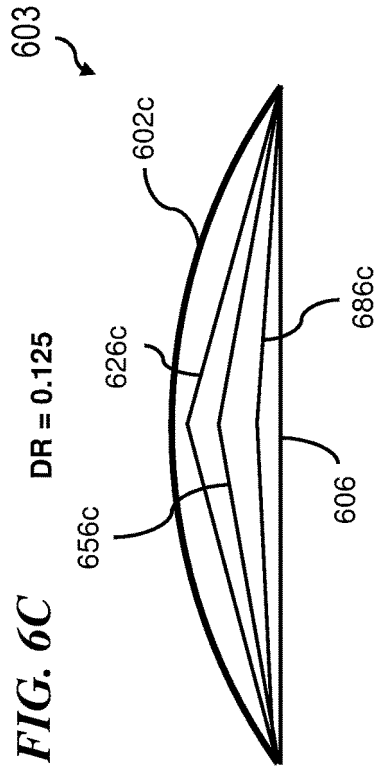
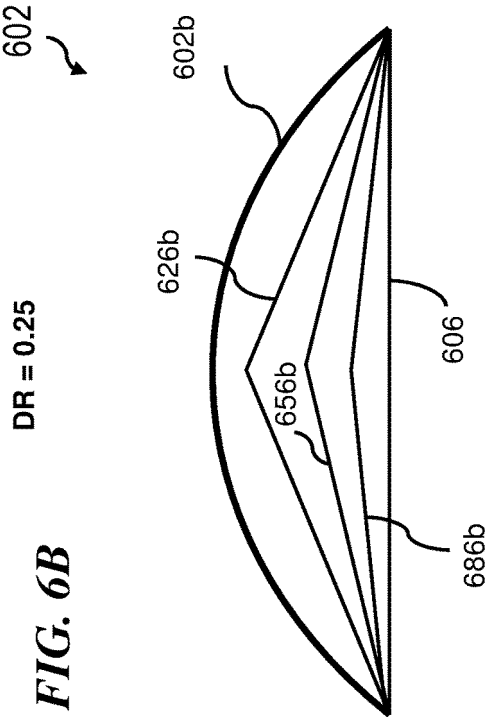
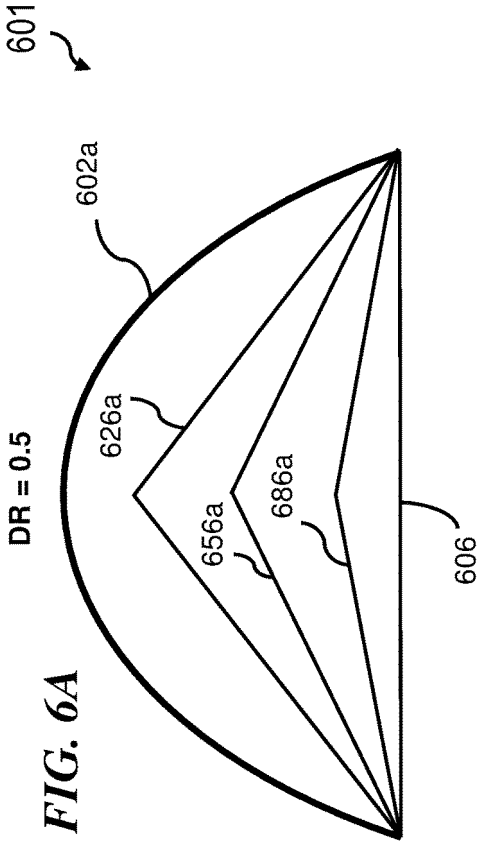


FIG. 7

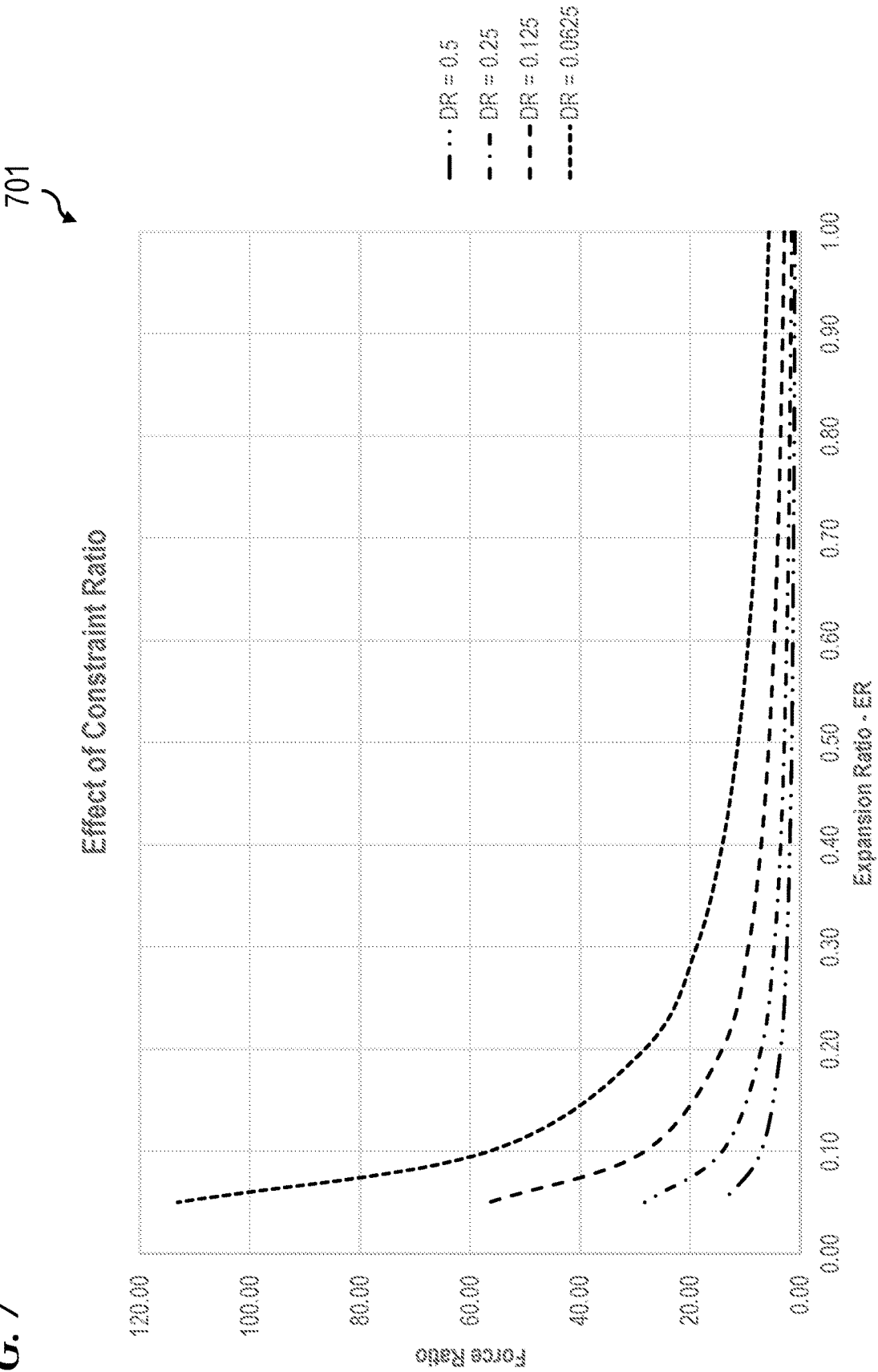


FIG. 8A

800

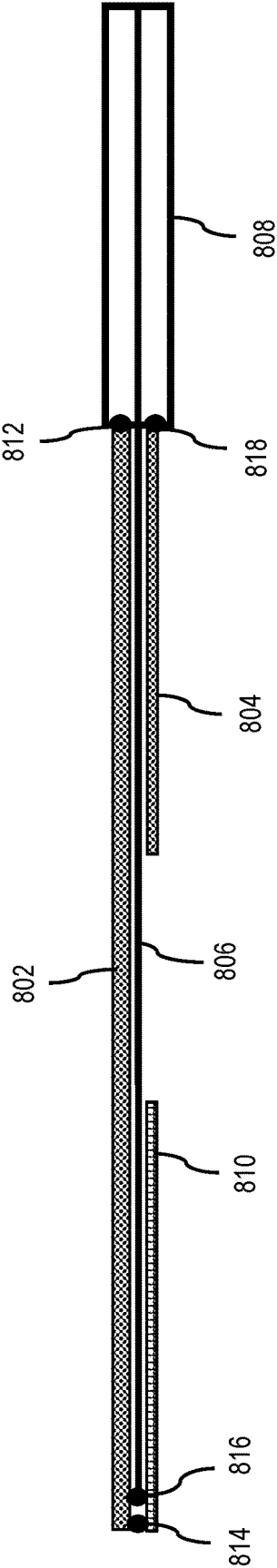


FIG. 8B

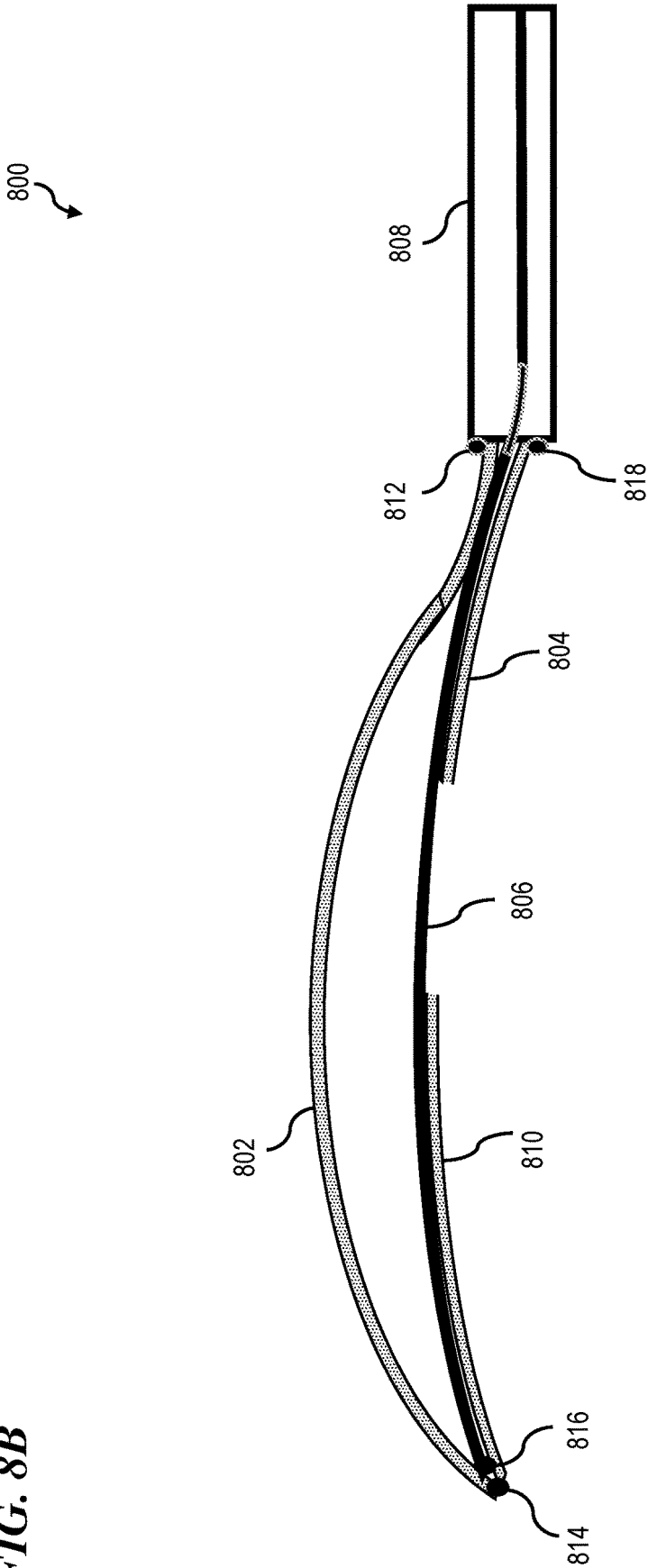


FIG. 9A

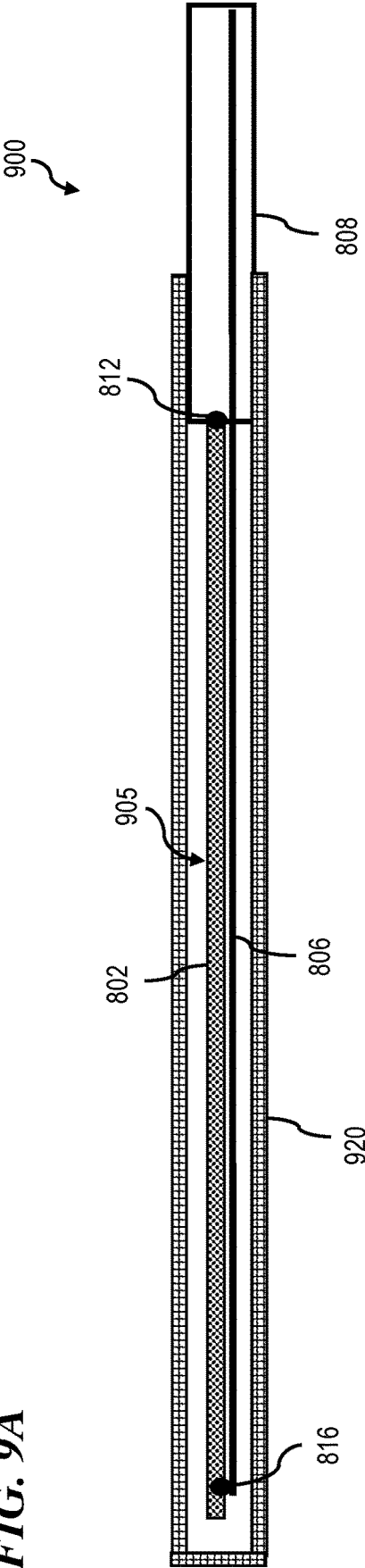


FIG. 9B

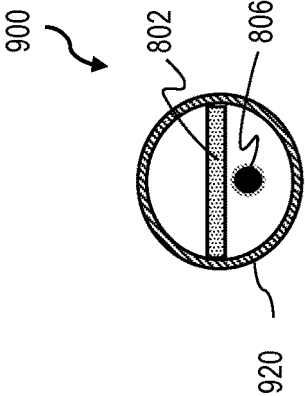


FIG. 9C

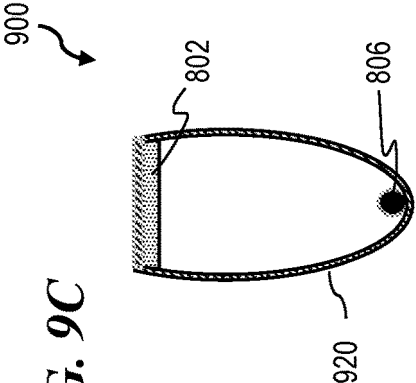


FIG. 10A

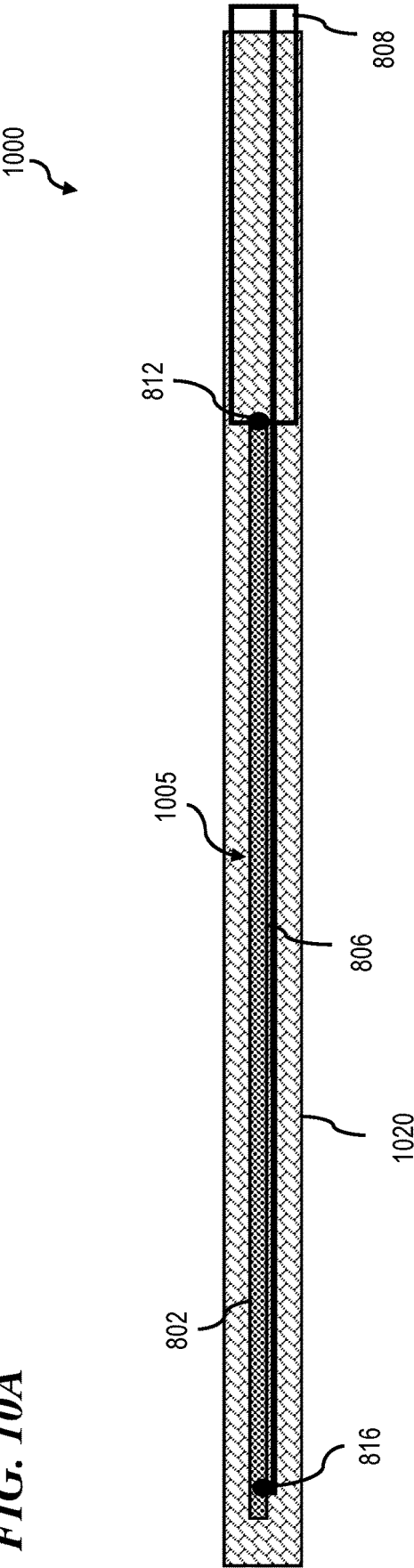


FIG. 10B

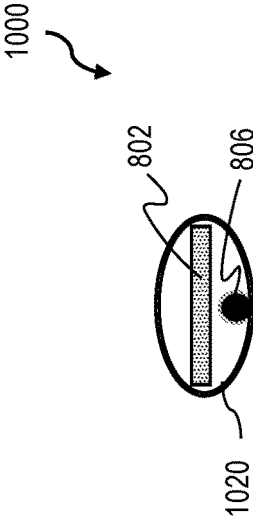


FIG. 10C

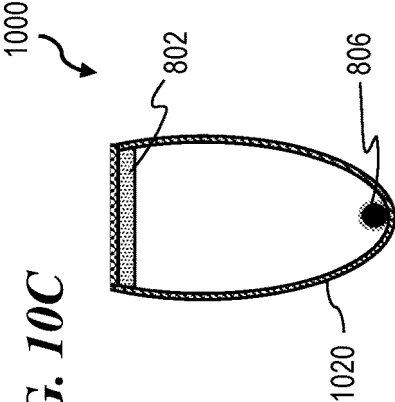




FIG. 11A

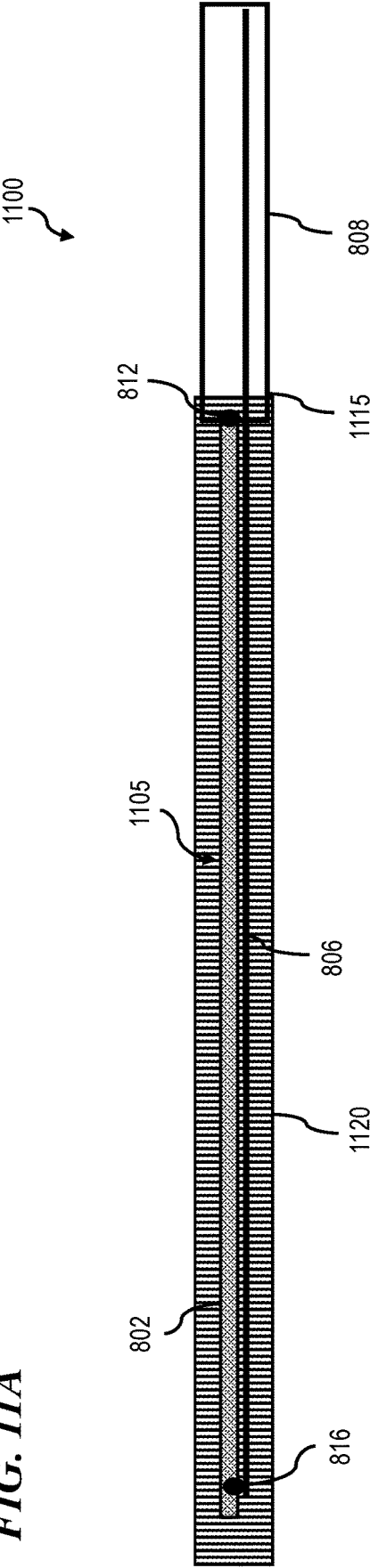


FIG. 11B

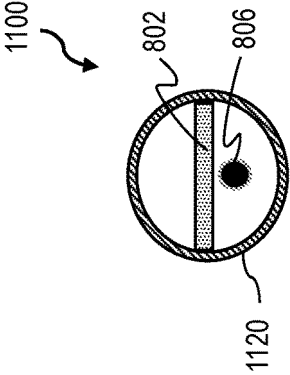


FIG. 11C

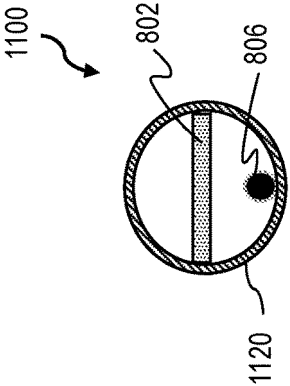


FIG. 12A

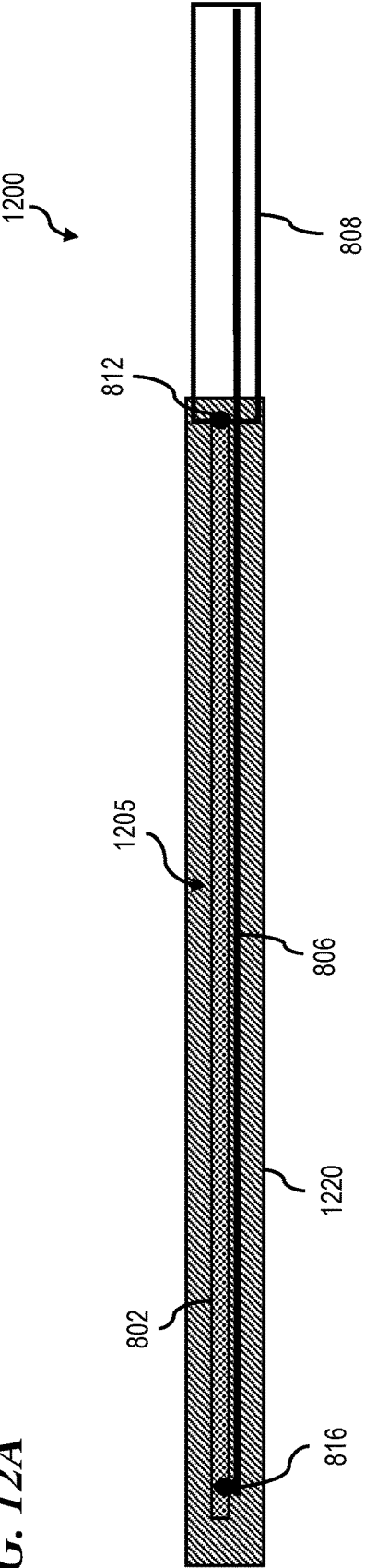


FIG. 12B

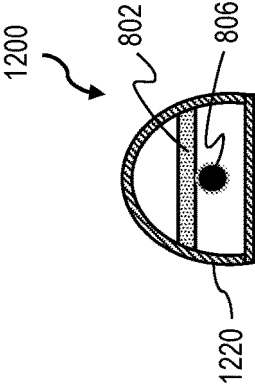


FIG. 12C

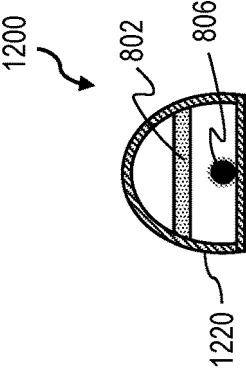


FIG. 12D

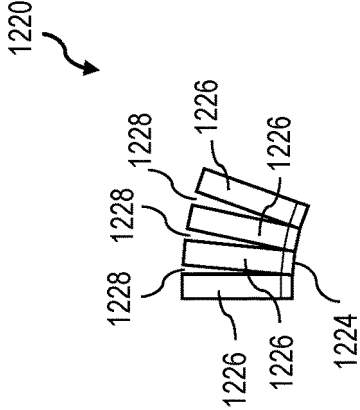


FIG. 13A

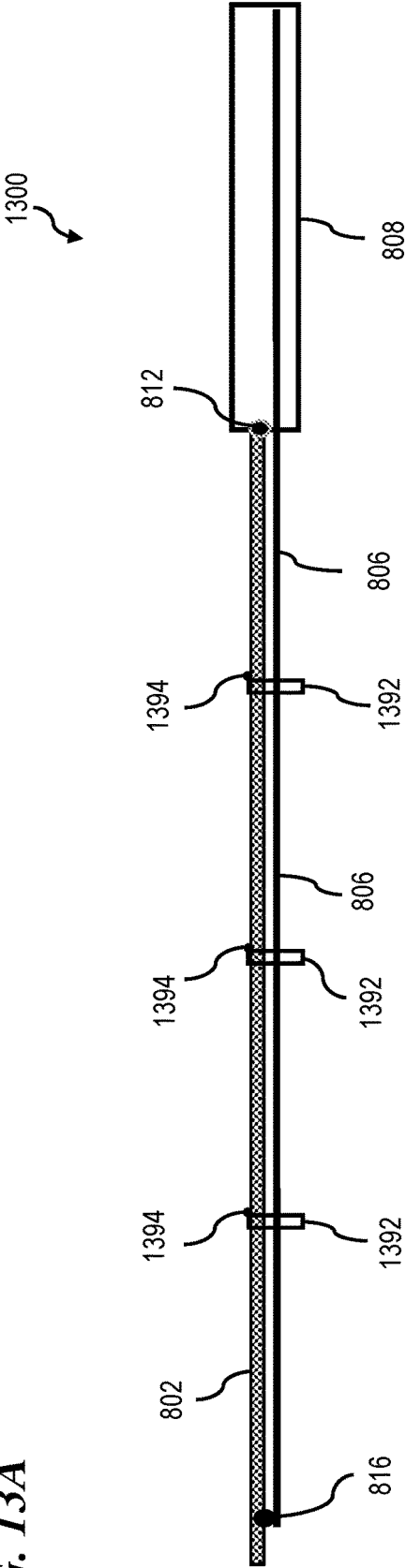


FIG. 13B

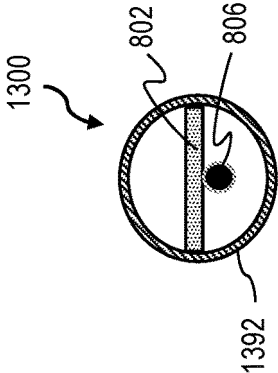


FIG. 13C

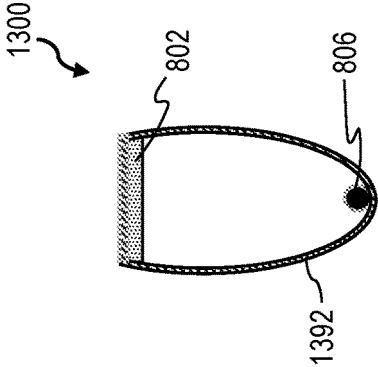


FIG. 13D

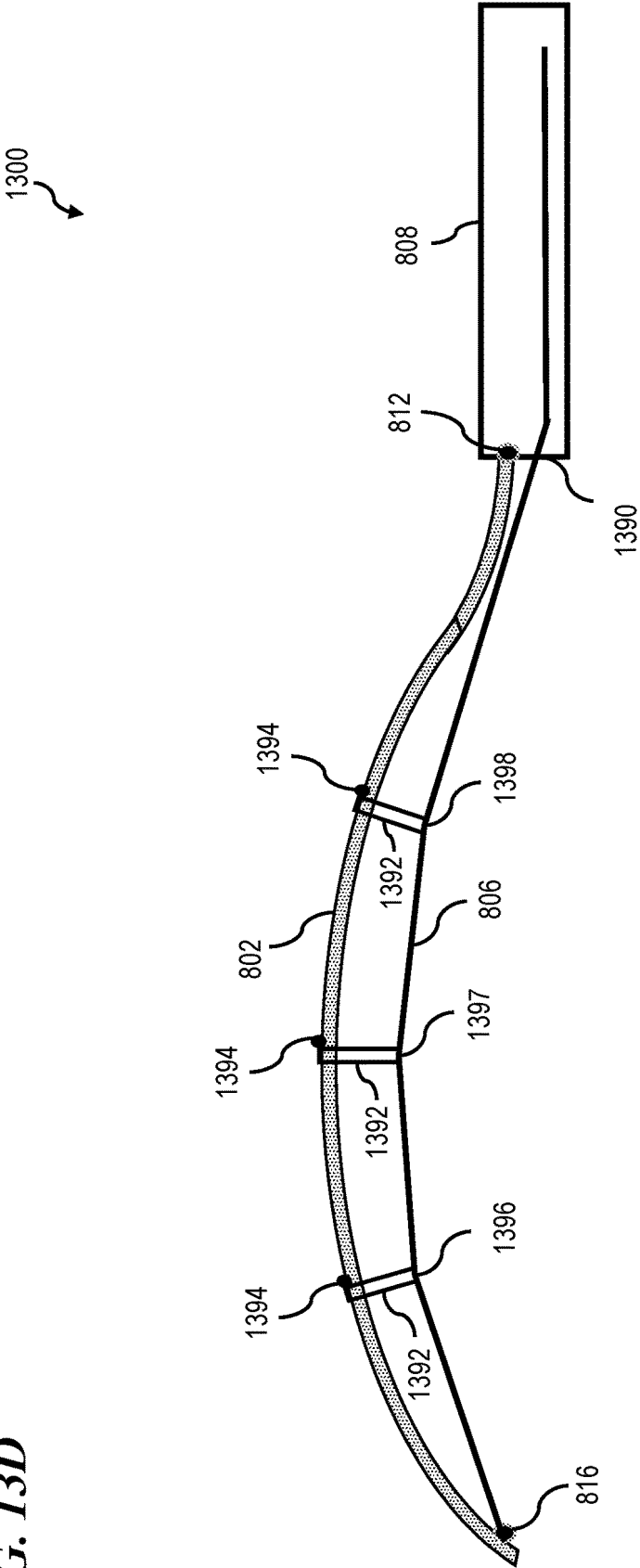


FIG. 14A

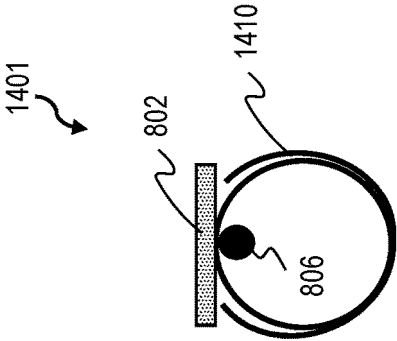


FIG. 14B

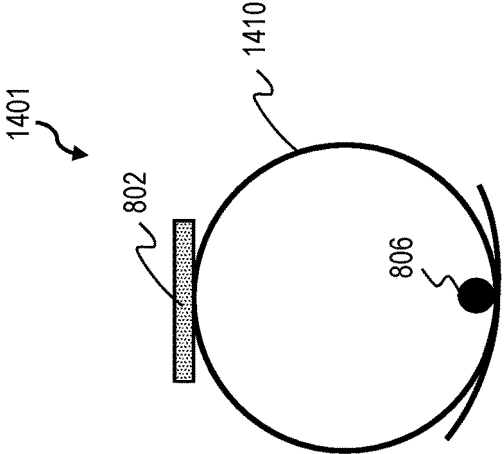


FIG. 14C

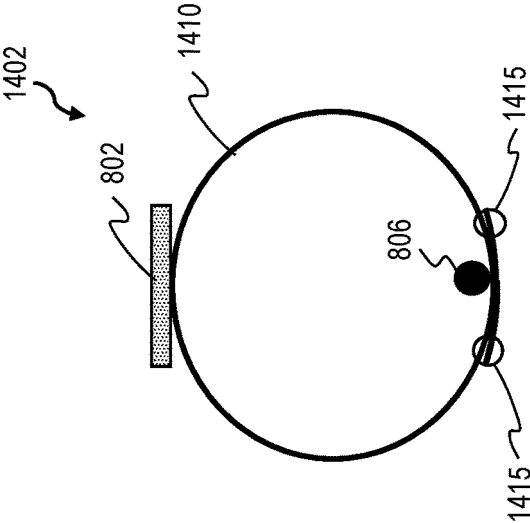


FIG. 15A

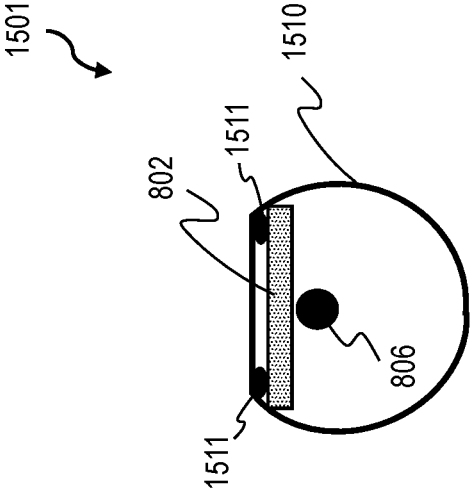


FIG. 15B

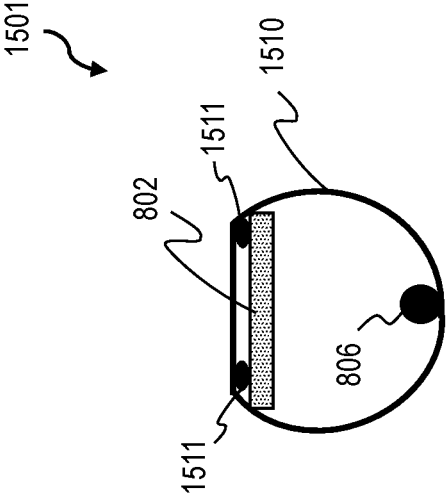


FIG. 16

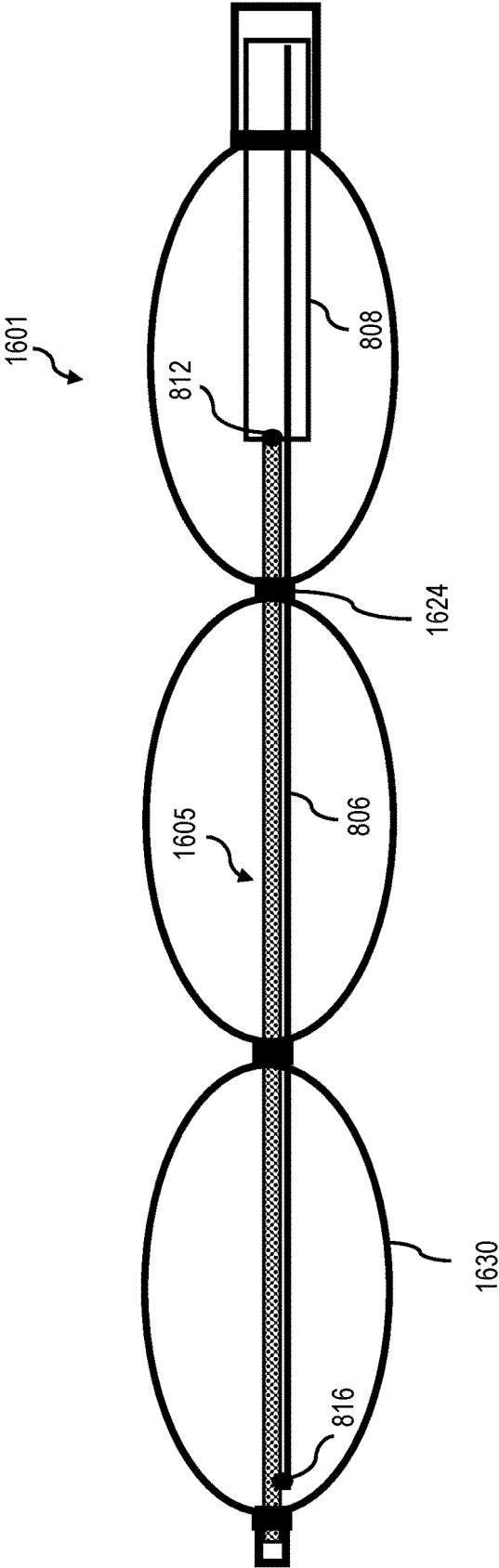


FIG. 17

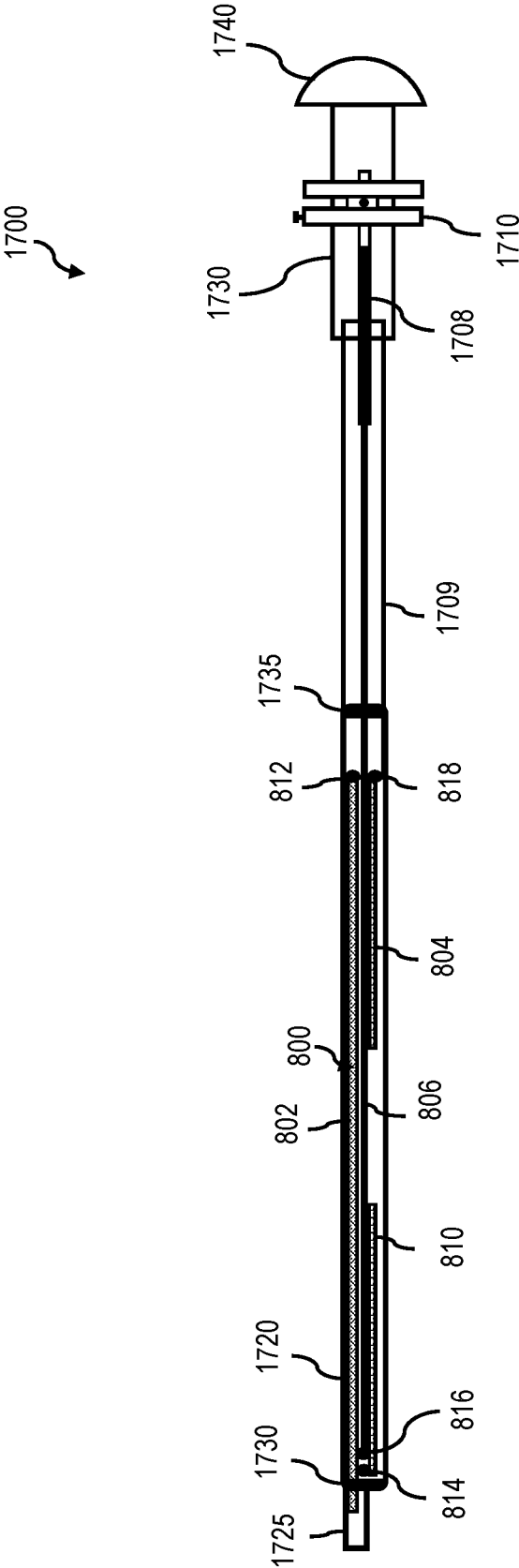
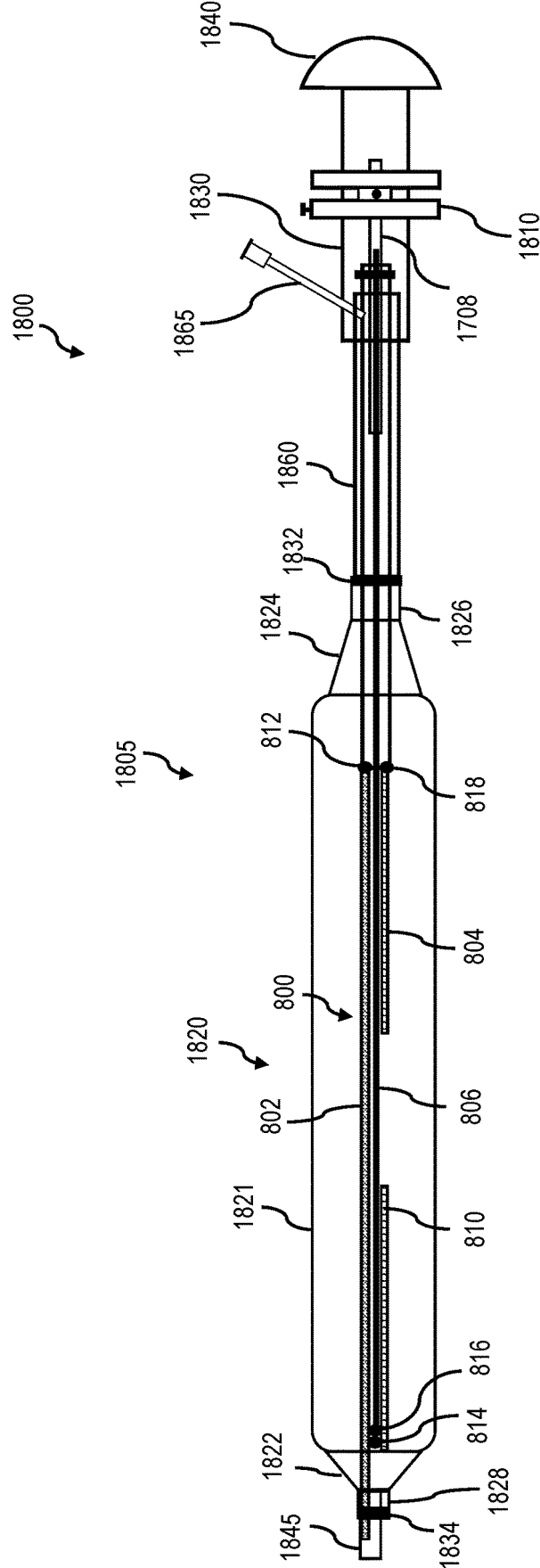




FIG. 18



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# SYSTEM AND METHOD FOR DEFLECTION MECHANISM WITH EXPANDABLE CONSTRAINT

## CROSS-REFERENCE TO RELATED APPLICATIONS

This application claims priority benefit, under 35 U.S.C. § 119(e), of U.S. Provisional Patent Application No. 63/223,383, filed Jul. 19, 2021 by Gregory G. Brucker et al., titled “SYSTEM AND METHOD FOR DEFLECTION MECHANISM WITH EXPANDABLE CONSTRAINT,” which is incorporated herein by reference in its entirety.

This application is related to prior:

U.S. Provisional Patent Application 62/426,223, titled “SYSTEM AND METHOD FOR DEFLECTION OF A BODY LUMEN” filed Nov. 23, 2016;

PCT Patent Application PCT/US2017/063171, titled “SYSTEM AND METHOD FOR DEFLECTION OF A BODY LUMEN” filed Nov. 23, 2017 (published as WO 2018/098388); and

U.S. Pat. No. 11,298,203, issued Apr. 12, 2022 to Gregory G. Brucker et al. and titled “SYSTEM AND METHOD FOR DEFLECTION OF A BODY LUMEN; each of which is incorporated herein by reference in its entirety.

There are multiple embodiments described herein, each of which can be combined with one or more other embodiments described herein and/or incorporated by reference. In some other embodiments, the present invention provides subcombinations that include most features of the various embodiments, but omit one or more features that are individually shown and described herein.

## FIELD OF THE INVENTION

The present invention relates generally to a mechanism for deflection of a body lumen, and in particular to a deflection mechanism and method that provides greater mechanical advantage with which to deflect the body lumen while also limiting the maximum distance the deflection mechanism can move in order to keep the deflection-mechanism movement consistent with the dimensions of the body lumen.

## BACKGROUND OF THE INVENTION

In one embodiment of an esophageal, deflection catheter system **101**, system **101** is comprised of two independent parts: namely a balloon catheter **105** and a deflection mechanism **160** as shown in FIG. 1. Deflection mechanism **160** includes a beam affixed to a metal tube at its proximal end to anchor the beam and affixed to a pull wire at its distal end to deflect the beam (the beam, metal tube, and pull wire are not shown in FIG. 1 since these components are primarily contained within catheter shaft **121**). Balloon catheter **105** includes a catheter shaft **121** comprised of a plastic tube to which is attached one or more balloons **170**. In some embodiments, a Tuohy Borst hub **140** is attached to the proximal end of the catheter shaft **121**, and, in some embodiments, deflection mechanism **160** includes a handle **165** coupled to hub **140**. In some embodiments, catheter shaft **121** includes metal bands **123** interspersed between balloons **170** and also distal to the most distal balloon and proximal to the most proximal balloon **170** such that each balloon **170** is demarcated by a metal ring **123** on either side of the balloon **170** for purposes of visualization, such as by fluoroscopy. In some embodiments, one or more skive hole(s)

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**124** serves as a port through which fluids are injected into or extracted from the luminal volume between two balloons and the interior surface of a body lumen. In some embodiments, catheter shaft **121** includes one or more ports **125** configured for injection or extraction of fluids. In some embodiments, balloons **170** are in fluid communication with a port within the hub **140** to inflate/deflate the balloons. In some embodiments, the central lumen of catheter shaft **121** contains the beam and pull wire of deflection mechanism **160**. The maneuverability of the deflection mechanism **160** allows it to be positioned within the balloon catheter **105** and deflected to achieve the desired spatial position, for example, a deflected esophagus in a thoracic cavity relative to the posterior wall of the heart.

In operation, when esophageal deflection is desired, the balloon catheter **105** is inserted through the throat into the esophagus and positioned at a desired location relative to the heart. The balloon(s) are inflated to expand the esophagus in order to maintain a circular cross-sectional profile during deflection. The deflection mechanism **160** is then positioned both longitudinally and rotationally within the catheter **105** to achieve the desired deflection of the esophagus relative to the posterior wall of the heart. The said esophageal deflection allows cardiac ablation on the posterior wall of the heart to be performed safely and more effectively to treat atrial fibrillation. Movement of the esophagus is achieved by tensioning a pull wire of deflection mechanism **160** which causes the beam to curve into an arc which in turn causes the catheter to deflect away from its centerline. Increasing tension on the pull wire increases the depth of the arc causing a larger deflection from the centerline of the catheter **105**. Similarly, deflection of other body lumens relative to critical structures can be obtained using deflection catheter system **101**. When positioned inside a body lumen, the body lumen moves in conjunction with deflection catheter system **101**.

One issue encountered with this design is the difficulty of deflecting a body lumen which is externally constrained by other structures or body tissue such as by connective tissue surrounding the esophagus. This situation contrasts with that of a steerable catheter, such as those used in electrophysiology for cardiac ablation or in angioplasty for treatment of coronary artery disease, in which the deflection mechanism is used to redirect a catheter tip to achieve a desired location. Many body lumens, including the esophagus, have fibrous connections to surrounding tissue which generate external forces which must be overcome to achieve the desired degree of translation. These additional forces on the deflection catheter alter the distribution of mechanical forces within the deflection mechanism, resulting in a significant increase in pull forces required to deflect the body lumen. This required increased pull force is generally difficult to achieve with current deflectable catheter designs because the pull wire in these designs is tightly constrained by a catheter body structure, reducing the ability of the pull wire to gain mechanical advantage to assist in deflecting a body lumen.

The effect of the lack of mobility of a pull wire imposed by a balloon catheter on a deflection mechanism can be best understood in accordance with FIG. 2A through FIG. 3. FIG. 2A illustrates a design of the distal end of a typical deflection mechanism **200** in its neutral state, i.e., no curvature. Deflection mechanism **200** includes beam **202** of a fixed length defined by the desired length of a deflected body lumen to which support tube **208** is attached on its proximal end by means of joint **212**. Support tube **208** extends to the handle of the deflection mechanism **200** (not shown) where it is fixed within a handle (not shown). Pull wire **206** is anchored

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to the distal end of beam **202** at joint **216**. Pull wire **206** runs along beam **202**, through center of the support tube **208**, through the handle (not shown) and terminates in a sliding mechanism (not shown) which is used to tension pull wire **206** to deflect a beam **202** and hence a body lumen.

FIG. **2B** illustrates a deflection mechanism **200** which has been deflected a certain distance from its neutral or straight state. In this configuration, during deflection, pull wire **206** is tensioned using a slide mechanism in a handle (not shown). Because the length of pull wire **206** shortens between points **212** and **216**, beam **202** curves to form an arc defined by end points **212** and **216**. Because there are no constraints on lateral movement of pull wire **206** away from beam **202**, the pull wire forms a chord to the arc defined by points **216** and **212**. The resulting curvature of beam **202** is the mechanism by which deflection displaces a body lumen laterally away from its longitudinal axis. This configuration represents the maximum distance a pull wire **206** can be displaced from beam **202** in a curved or deflected configuration.

FIG. **3** illustrates a deflection mechanism **300** in which pull wire expansion (i.e., the distance between pull wire **206** and beam **202**) is constrained by an internal lumen of a catheter shaft. In this configuration, the internal wall of catheter lumen **320** acts to limit the lateral movement of pull wire **206** away from beam **202** during deflection. Because of this constraint, pull wire **206** assumes the shape of an arc as shown in FIG. **3** instead of a chord as shown in FIG. **2B**. This change in orientation of pull wire **206** relative to beam **202** in FIG. **3** results in higher tensile forces in the pull wire for the same beam curvature when compared to an unconstrained pull wire **206** as shown in FIG. **2B**. This difference (i.e., the difference in tensile forces) is rooted in the physics of beam deflection in which forces perpendicular to a beam cause displacement or curvature, the perpendicular force being higher in an unconstrained pull wire configuration.

U.S. Pat. No. 4,930,521 by William T. Metzger et al., titled "VARIABLE STIFFNESS ESOPHAGEAL CATHETER", issued on Jun. 5, 1990 and is incorporated herein by reference.

U.S. Pat. No. 5,467,763 by Michael J. McMahon et al., titled "SURGICAL INSTRUMENTS", issued on Nov. 21, 1995 and is incorporated herein by reference.

U.S. Pat. No. 5,558,665 by Maciej J. Kieturakis, titled "SURGICAL INSTRUMENT AND METHOD FOR INTRALUMINAL RETRACTION OF AN ANATOMIC STRUCTURE", issued on Sep. 24, 1996 and is incorporated herein by reference.

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U.S. Pat. No. 7,621,908 by Steven W. Miller, titled "CATHETER FOR MANIPULATION OF THE ESOPHAGUS", issued on Nov. 24, 2009 and is incorporated herein by reference.

U.S. Pat. No. 8,273,016 by Martin F. O'Sullivan, titled "ESOPHAGUS ISOLATION DEVICE", issued on Sep. 25, 2012 and is incorporated herein by reference.

U.S. Pat. No. 8,454,588 by Gregory B. Rieker et al., titled "METHOD AND APPARATUS TO PREVENT ESOPHAGEAL DAMAGE", issued on Jun. 4, 2013 and is incorporated herein by reference.

U.S. Pat. No. 8,506,589 by James D. Maloney, titled "NASOGASTRIC TUBE FOR USE DURING AN ABLATION PROCEDURE", issued on Aug. 13, 2013 and is incorporated herein by reference.

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U.S. Pat. No. 8,529,443 by James D. Maloney, titled "NASOGASTRIC TUBE FOR USE DURING AN ABLATION PROCEDURE", issued on Sep. 10, 2013 and is incorporated herein by reference.

U.S. Pat. No. 9,668,720 by James F. Kasic, titled "SYSTEMS, DEVICES, COMPONENTS AND METHODS FOR DISPLACING AND REPOSITIONING THE ESOPHAGUS AWAY FROM THE HEART DURING ATRIAL ABLATION SURGICAL PROCEDURES", issued on Jun. 6, 2017 and is incorporated herein by reference.

U.S. Pat. No. 9,744,339 by Shawn P. Fojtik, titled "APPARATUS FOR MANUALLY MANIPULATING HOLLOW ORGANS", issued on Aug. 29, 2017 and is incorporated herein by reference.

U.S. Pat. No. 9,833,149 by Shawn P. Fojtik et al., titled "METHODS, APPARATUS AND SYSTEMS FOR FACILITATING INTRODUCTION OF SHAPED MEDICAL INSTRUMENTS INTO THE BODY OF A SUBJECT", issued on Dec. 5, 2017 and is incorporated herein by reference.

U.S. Pat. No. 9,931,108 by Steven Miller, titled "SYSTEM AND METHOD FOR INFLUENCING AN ANATOMICAL STRUCTURE", issued on Apr. 3, 2018 and is incorporated herein by reference.

U.S. Pat. No. 9,937,329 by Imran K. Niazi, titled "INTRA-ESOPHAGEAL BALLOON SYSTEM", issued on Apr. 4, 2018 and is incorporated herein by reference.

U.S. Pat. No. 10,265,058 by James F. Kasic, titled "SYSTEMS, DEVICES, COMPONENTS AND METHODS FOR DISPLACING AND REPOSITIONING THE ESOPHAGUS AWAY FROM THE HEART DURING ATRIAL ABLATION SURGICAL PROCEDURES", issued on Apr. 23, 2019 and is incorporated herein by reference.

U.S. Pat. No. 10,307,149 by James F. Kasic et al., titled "INTRALUMINAL RETRACTOR", issued on Jun. 4, 2019 and is incorporated herein by reference.

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U.S. Pat. No. 10,335,133 by Shawn P. Fojtik, titled "EXPANDABLE DEVICES FOR POSITIONING ORGANS", issued on Jul. 2, 2019 and is incorporated herein by reference.

U.S. Pat. No. 10,695,041 by Shawn P. Fojtik, titled "EXPANDABLE DEVICES FOR POSITIONING ORGANS", issued on Jun. 30, 2020 and is incorporated herein by reference.

U.S. Patent Application Publication 2014/0094839 by Shekhar Nimkar et al., titled "MECHANICAL TENSIONING DEVICE", published on Apr. 3, 2014 and is incorporated herein by reference.

## SUMMARY OF THE INVENTION

In one embodiment of the present invention, a deflection mechanism with expandable constraints for manipulating a body lumen is comprised of a beam, a pull wire and one or more expandable constraints. In some embodiments, the expandable constraints are designed to allow a pull wire to move away from the beam during deflection to provide greater mechanical advantage with which to deflect the beam but limit the maximum distance the pull wire can move to a value less than that achievable in the absence of constraints. The advantage of this design is a reduction in force a pull wire must exert on a beam to deflect a body lumen, especially one constrained within a body cavity

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along its length, for example by connective tissue. Another advantage of a dynamically expandable constraint is maintenance of a smaller device diameter in its non-deflected state, allowing for easier introduction into a body cavity.

In another embodiment of the present invention for use in a clinical setting, the deflection mechanism is covered with a thin-walled flexible tube to prevent fluid infiltration and damage to the deflection mechanism or surrounding tissue during clinical use.

In some embodiments of a deflection mechanism with expandable constraints according to the present invention, a deflection mechanism with expandable constraints is combined with a catheter containing an expandable element for the purpose of deflecting a body lumen. In some embodiments of this concept, the invention includes a catheter shaft having a first lumen within the catheter shaft extending through at least a length of the catheter shaft, at least one inflatable and deflatable balloon located along the catheter shaft and operably coupled to said first lumen and configured to expand in diameter within a target lumen to form an expanded first portion of the apparatus, and a lateral deflection mechanism operably coupled within a catheter shaft, wherein the lateral deflection mechanism includes a beam, a pull wire, and expandable constraint(s) operably coupled to the beam and pull wire, wherein the expandable constraints permit movement of the pull wire away from the beam while also limiting the distance the pull wire can travel to a value less than the maximum possible distance in the absence of constraints.

In some embodiments of a deflection mechanism with expandable constraints according to the present invention for deflection of a body lumen, the combination of a deflection mechanism and balloon catheter are designed to combine a mechanical approach with an expandable-element approach to obtain the benefits of more reliable positioning, larger body lumen deflection and easier clinical use. These benefits are derived from features which collectively provide the following desirable clinical advantages: First is an expansion catheter that includes a catheter shaft with one or more expansion elements along its outer surface. The expansion element(s) serve to enlarge a body lumen to reduce its elasticity and deformability when manipulated, effectively fixing the relationship between the expansion catheter and the body lumen. Second is a deflection mechanism which resides within a catheter shaft which, when manipulated, causes the catheter shaft to deviate from its neutral state to a curved state in which a least a portion of the catheter shaft is displaced laterally while simultaneously displacing a body lumen in contact with the expansion element(s). Third is an expansion element and deflection mechanism which are movable with respect to each other in order to locate and more easily deflect a portion of a catheter relative to a body structure. Fourth is a deflection mechanism which contains expandable constraints on lateral movement of a pull wire which allow the pull wire to move away from the beam to achieve a larger mechanical advantage to more effectively utilize the tensile force of a pull wire to deflect the beam within the confines of a body luminal diameter. Fifth is a smaller device diameter in its non-deflected state for ease of introduction into a body lumen.

#### BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a schematic diagram of a deflection catheter system 101.

FIG. 2A is a schematic diagram of the distal end of a typical deflection mechanism 200 in its neutral state.

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FIG. 2B is a schematic diagram of deflection mechanism 200 that has been deflected a certain distance from its neutral or straight state.

FIG. 3 is a schematic diagram of a deflection mechanism 300 in which pull wire expansion is constrained by an internal lumen of a catheter shaft.

FIG. 4A is a schematic diagram 401 showing the forces associated with a deflection beam having an attached pull wire, according to one embodiment of the present invention.

FIG. 4B is a schematic diagram 402 showing the forces associated with the unconstrained configuration of deflection mechanism 200 of FIG. 2B, according to one embodiment of the present invention.

FIG. 4C is a schematic diagram 403 showing the forces associated with the constrained configuration of deflection mechanism 300 of FIG. 3, according to one embodiment of the present invention.

FIG. 5 is a schematic diagram of a deflection mechanism 501, according to one embodiment of the present invention.

FIG. 6A is a schematic diagram showing a deflection configuration 601 having a depth ratio of 0.5, according to one embodiment of the present invention.

FIG. 6B is a schematic diagram showing a deflection configuration 602 having a depth ratio of 0.25, according to one embodiment of the present invention.

FIG. 6C is a schematic diagram showing a deflection configuration 603 having a depth ratio of 0.125, according to one embodiment of the present invention.

FIG. 6D is a schematic diagram showing a deflection configuration 604 having a depth ratio of 0.0625, according to one embodiment of the present invention.

FIG. 7 is a graph 701 showing the effect on pull wire tensile force to deflect an esophagus over a length of 12 cm for various deflection distances, DR, and variable degrees of constraint, ER, the range of which is illustrated in FIG.'s 6A-6D, according to one embodiment of the present invention.

FIG. 8A is a schematic diagram showing a deflection mechanism 800, according to one embodiment of the present invention.

FIG. 8B is a schematic diagram of deflection mechanism 800 in a tensioned state, according to one embodiment of the present invention.

FIG. 9A is a schematic diagram of a deflection assembly 900, according to one embodiment of the present invention.

FIG. 9B is a cross-sectional view of deflection assembly 900 as viewed toward the right-hand side of FIG. 9A from the middle of deflection assembly 900, with beam 802 in its neutral or undeflected state, according to one embodiment of the present invention.

FIG. 9C is a cross-sectional view of deflection assembly 900 as viewed toward the right-hand side of FIG. 9A from the middle of deflection assembly 900, with beam 802 in its deflected state and pull wire 806 moved laterally away from beam 802, according to one embodiment of the present invention.

FIG. 10A is a schematic diagram of a deflection assembly 1000, according to one embodiment of the present invention.

FIG. 10B is a cross-sectional view of deflection assembly 1000 as viewed toward the right-hand side of FIG. 10A from the middle of deflection assembly 1000, with beam 802 in its neutral or undeflected state, according to one embodiment of the present invention.

FIG. 10C is a cross-sectional view of deflection assembly 1000 as viewed toward the right-hand side of FIG. 10A from the middle of deflection assembly 1000, with beam 802 in its



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deflected state and pull wire **806** moved laterally away from beam **802**, according to one embodiment of the present invention.

FIG. **11A** is a schematic diagram of a deflection assembly **1100**, according to one embodiment of the present invention.

FIG. **11B** is a cross-sectional view of deflection assembly **1100** as viewed toward the right-hand side of FIG. **11A** from the middle of deflection assembly **1100**, with beam **802** in its neutral or undeflected state, according to one embodiment of the present invention.

FIG. **11C** is a cross-sectional view of deflection assembly **1100** as viewed toward the right-hand side of FIG. **11A** from the middle of deflection assembly **1100**, with beam **802** in its deflected state and pull wire **806** moved laterally away from beam **802**, according to one embodiment of the present invention.

FIG. **12A** is a schematic diagram of a deflection assembly **1200**, according to one embodiment of the present invention.

FIG. **12B** is a cross-sectional view of deflection assembly **1200** as viewed toward the right-hand side of FIG. **12A** from the middle of deflection assembly **1200**, with beam **802** in its neutral or undeflected state, according to one embodiment of the present invention.

FIG. **12C** is a cross-sectional view of deflection assembly **1200** as viewed toward the right-hand side of FIG. **12A** from the middle of deflection assembly **1200**, with beam **802** in its deflected state and pull wire **806** moved laterally away from beam **802**, according to one embodiment of the present invention.

FIG. **12D** is a magnified cross-sectional view of a portion of plastic tube **1220** showing segments **1226** and cuts **1228**, according to one embodiment of the present invention.

FIG. **13A** is a schematic diagram of a deflection assembly **1300** in a neutral or undeflected state, according to one embodiment of the present invention.

FIG. **13B** is a cross-sectional view of deflection assembly **1300** as viewed toward the right-hand side of FIG. **13A** from the middle of deflection assembly **1300**, with beam **802** in its neutral or undeflected state, according to one embodiment of the present invention.

FIG. **13C** is a cross-sectional view of deflection assembly **1300** as viewed toward the right-hand side of FIG. **13A** from the middle of deflection assembly **1300**, with beam **802** in its deflected state and pull wire **806** moved laterally away from beam **802**, according to one embodiment of the present invention.

FIG. **13D** is a schematic diagram of deflection assembly **1300** in its deflected state, according to one embodiment of the present invention.

FIG. **14A** is a cross-sectional view of a deflection assembly **1401** with beam **802** in its neutral or undeflected state, according to one embodiment of the present invention.

FIG. **14B** is a cross-sectional view of deflection assembly **1401** with beam **802** in its deflected state and pull wire **806** moved laterally away from beam **802**, according to one embodiment of the present invention.

FIG. **14C** is a cross-sectional view of a deflection assembly **1402** with beam **802** in its deflected state and pull wire **806** moved laterally away from beam **802**, according to one embodiment of the present invention.

FIG. **15A** is a cross-sectional view of a deflection assembly **1501** with beam **802** in its neutral or undeflected state, according to one embodiment of the present invention.

FIG. **15B** is a cross-sectional view of deflection assembly **1501** with beam **802** in its deflected state, according to one embodiment of the present invention.

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FIG. **16** is a schematic diagram of a deflection assembly **1601**, according to one embodiment of the present invention.

FIG. **17** is a schematic diagram of a deflection assembly **1700**, according to one embodiment of the present invention.

FIG. **18** is a schematic diagram of a deflection assembly **1800**, according to one embodiment of the present invention.

## DETAILED DESCRIPTION

Although the following detailed description contains many specifics for the purpose of illustration, a person of ordinary skill in the art will appreciate that many variations and alterations to the following details are within the scope of the invention. Specific examples are used to illustrate particular embodiments; however, the invention described in the claims is not intended to be limited to only these examples, but rather includes the full scope of the attached claims. Accordingly, the following embodiments of the invention are set forth without any loss of generality to, and without imposing limitations upon the claimed invention. Further, in the following detailed description of the embodiments, reference is made to the accompanying drawings that form a part hereof, and in which are shown by way of illustration specific embodiments in which the invention may be practiced. It is understood that other embodiments may be utilized and structural changes may be made without departing from the scope of the present invention. The embodiments shown in the Figures and described here may include features that are not included in all specific embodiments. A particular embodiment may include only a subset of all of the features described, or a particular embodiment may include all of the features described.

The leading digit(s) of reference numbers appearing in the Figures generally corresponds to the Figure number in which that component is first introduced, such that the same reference number is used throughout to refer to an identical component which appears in multiple Figures. Signals and connections may be referred to by the same reference number or label, and the actual meaning will be clear from its use in the context of the description.

Certain marks referenced herein may be common-law or registered trademarks of third parties affiliated or unaffiliated with the applicant or the assignee. Use of these marks is for providing an enabling disclosure by way of example and shall not be construed to limit the scope of the claimed subject matter to material associated with such marks.

In most conventional deflectable catheters, a thin wire is used to apply a force to a catheter shaft to deflect a distal portion from its longitudinal axis, causing a change in shape for the purpose of redirecting a catheter within a body cavity. A pull wire is typically housed within a small lumen in a catheter shaft causing the pull wire to be highly constrained by the luminal walls of the catheter and thus remain parallel to the longitudinal axis of the catheter. This constrained alignment of the pull wire causes most of its force to be directed along the catheter longitudinal axis, with only a small force directed perpendicular to the axis for the purpose of changing the shape of its distal region. For most applications this applied force is adequate to manipulate the tip of a catheter, for example to steer a tip for the purpose of redirecting a catheter over a small distance. However, for some applications, this force is inadequate to achieve larger deflections of a body lumen over longer distances, for example, esophageal deflection requiring 6 cm deflection over a distance of 16 cm. This situation is compounded by forces created by connective tissues which are present to stabilize a body lumen, forces which also must be overcome

to deflect a body lumen. One way to overcome this limitation is to provide a larger mechanical advantage for a pull wire, for example by allowing the pull wire to operate in larger space, thereby increasing the percentage of the pull wire force directed laterally rather than longitudinally. For most catheter designs, which are made of harder-durometer materials with little elasticity and small overall diameters, this is very difficult to achieve. One goal of the present invention is to provide a deflection mechanism with an expandable constraint which allows a pull wire to occupy a much larger space during deflection to provide more lateral movement of a pull wire to gain mechanical advantage, but still limit a pull wire to movement consistent with the dimensions of a body lumen.

The effect of a constraint on deflection forces in a beam is more easily understood with reference to FIGS. 4A-4C. FIG. 4A shows a force diagram 401 illustrating a distal end of a beam with an attached pull wire, according to one embodiment of the present invention. The tensile force,  $T_{wire}$ , of FIG. 4A can be resolved into a force perpendicular to the beam,  $F_{per}$ , which is the force that deflects the beam and a force parallel to the beam,  $F_{par}$  which creates tension in the pull wire. These two orthogonal forces are related to the tensile force in the wire,  $T_{wire}$ , by an angle  $\Theta$ , the angle that the pull wire makes with the beam as shown in FIG. 4A. Using trigonometry, the tensile force in the wire can be resolved into its orthogonal components as follows:

$$F_{per}=T_{wire}\times\cos(\Theta)$$

$$F_{par}=T_{wire}\times\sin(\Theta)$$

Using these equations, the effect of a constraint on deflection forces can be illustrated in the context of an esophageal application in which a 2.5-cm-diameter esophagus is deflected 6 cm over a longitudinal distance of 16 cm by applying a 500 grams-force tensile force to pull wire 206 (as used herein, one (1) "gram-force" is equal to a mass of one gram multiplied by the standard acceleration due to gravity on Earth, which is 9.80665 meters per second squared ( $m/s^2$ ), and one (1) gram-force (gf) is equivalent to 0.00980665 newtons; accordingly, for example, 500 grams-force of tensile force is equivalent to 4.903325 newtons of tensile force).

FIG. 4B shows a force diagram 402 for the unconstrained configuration of FIG. 2B, according to one embodiment of the present invention. For this configuration, the angle  $\Theta$  is approximately 40 degrees, which yields a calculated perpendicular force  $F_{per}=383$  grams-force. FIG. 4C shows a force diagram 403 for the constrained configuration of FIG. 3 in which a deflection mechanism is contained within a catheter internal lumen having a diameter of 6 mm. For this configuration, the angle  $\Theta$  is approximately 86 degrees, which yields a perpendicular force  $F_{per}=35$  grams-force. Comparing forces, the constrained configuration results in an approximate 10-fold reduction in the perpendicular force for deflecting a beam.

Returning to the clinical application of esophageal deflection, in some embodiments a beam is 0.5 mm thick, 7 mm wide and 16 cm long. Using an equation for a simply supported beam with one end constrained, the force required to deflect the cited beam 6 cm is approximately 40 grams-force.

FIG. 4C is a schematic diagram 403 showing the forces associated with the constrained configuration of deflection mechanism 300 of FIG. 3, according to one embodiment of the present invention. As shown in FIG. 4C, even in a constrained configuration, a tension of 500 grams-force in

the pull-wire provides sufficient force to deflect the beam, a force which is reasonable to achieve in a typical deflection catheter. However, if 430 grams-force is applied perpendicular to the beam to simulate lateral forces imposed by esophageal body constraints, the beam must now overcome this additional 430 grams-force plus the deflection force of 40 grams-force in order to deflect the esophagus. For the unconstrained configuration of FIG. 4B, using an angle of 40 degrees, requires a tensile force of 613 grams-force to obtain a deflection force of 470 grams-force. For the constrained configuration of FIG. 4C, using an 86-degree angle, the pull wire tensile force becomes 6,737 grams-force to obtain a deflection force of 470 grams-force. This higher force for the constrained configuration is obtainable with mechanical advantage in the handle which would require significantly stronger materials of construction. While not prohibitive, this situation is less than desirable in a clinical setting, especially when alternatives are available which are less expensive and safer.

To better understand the effect of an expandable constraint on a pull wire in deflection of a body lumen, it is desirable to define terminology specific to this application.

FIG. 5 is a schematic diagram of a deflection mechanism 501, according to one embodiment of the present invention. Referring to FIG. 5, a parameter P is defined as the location on the beam of the largest displacement of pull wire 506 between endpoints 516 and 512 from beam 502. Another parameter,  $d_c$ , is defined as the perpendicular distance between the curved beam at point P and the pull wire shown as dotted line 506a in FIG. 5, which represents the position of a pull wire resulting from the use of constraints (not shown). In addition, parameters  $d_{c\ max}$  and  $P_{max}$  are defined as the values of  $d_c$  and P respectively for an unconstrained pull wire, which is equivalent to a chord connecting points 512 and 516. Another parameter  $L_b$  is defined as the linear distance of the beam between two end points 516 and 512 when the beam is in its neutral or non-deflected state.

Using these definitions, an expansion ratio, ER, is defined as the actual distance  $d_c$  in a constrained configuration to the maximum possible distance in a configuration without a constraint  $d_{c\ max}$ , which can be written as

$$ER=d_c/d_{c\ max}$$

In some embodiments of an esophageal application, the maximum unconstrained deflection is 6 cm. By definition this configuration has an  $ER=1.0$  because  $d_c=d_{c\ max}$ . If the deflection mechanism is placed inside a catheter with an internal lumen diameter of 5 mm, this configuration would have an ER value of 0.5/6 or 0.0833 assuming the pull wire movement is limited by the diameter of the internal lumen.

Another parameter referred to herein as depth ratio, DR, is defined as the maximum possible deflection obtainable by a deflection device divided by the chord length of the beam in its neutral state, which can be written as

$$DR=d_{c\ max}/L_b$$

In some embodiments of an esophageal application where a deflection of 6 cm is desired over a 15 cm length,  $DR=6/15=0.4$ .

Using this terminology, the advantages of a pull wire having the freedom to move laterally away from the beam during deflection is understood in the context of different deflection configurations shown in FIGS. 6A-6D.

FIG. 6A shows a deflection configuration 601 in which the depth of the curve  $d_{c\ max}$  of beam 602a is half the beam length, giving a DR ratio of 0.5, according to one embodiment of the present invention. The pull wire in the uncon-

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strained configuration, ER=1.0, is labelled **606**, the pull wire for ER=0.80 is labelled **686ab**, for ER=0.50 is labelled **656a**, and for ER=0.20 is labelled **626a**.

FIG. 6B shows a deflection configuration **602** in which the depth of the curve  $d_{c, max}$  of beam **602b** is one-fourth the length of the beam, giving a DR ratio of 0.25, according to one embodiment of the present invention. The pull wire in the unconstrained configuration is labelled **606**, the pull wire for ER=0.80 is labelled **686b**, for ER=0.50 is labelled **656b**, and for ER=0.20 is labelled **626b**.

FIG. 6C shows a deflection configuration **603** in which the depth of the curve  $d_{c, max}$  of beam **602c** is one-eighth the length of the beam, giving a DR ratio of 0.125, according to one embodiment of the present invention. The pull wire in the unconstrained configuration is labelled **606**, the pull wire for ER=0.80 is labelled **686c**, for ER=0.50 is labelled **656c**, and for ER=0.20 is labelled **626c**.

FIG. 6D shows a deflection configuration **604** in which the depth of the curve  $d_{c, max}$  of beam **602d** is one-sixteenth the length of the chord length, giving an DR ratio of 0.0625, according to one embodiment of the present invention. The pull wire in the unconstrained configuration is labelled **606**, the pull wire for ER=0.80 is labelled **686d**, for ER=0.50 is labelled **656d**, and for an ER=0.20 is labelled **626d**.

FIG. 7 is a graph **701** showing the effect on pull wire tensile force to deflect an esophagus over a length of 12 cm for various deflection distances, DR, and variable degrees of constraint, ER, the range of which is illustrated in FIGS. 6A-6D, according to one embodiment of the present invention. The horizontal axis represents the expansion ratio, ER. The vertical axis represents the Force Ratio, which is the perpendicular force a pull wire exerts on the beam normalized by the perpendicular force for the configuration DR=0.5 and an ER=1.0. In some embodiments, selection of this configuration for normalization has no other significance than making the data more understandable.

As can be seen in FIG. 7, the effect of an expandable constraint on a pull wire becomes more pronounced as the expansion ratio, ER, becomes smaller, i.e., the pull wire remains closer to the beam during deflection. In the configuration of FIG. 6A where the depth ratio has the largest value, the change in the normalized force between ER=1.0 and 0.1 is approximately 7 to 1, with the lowest ER value having the highest force. This configuration most closely represents that of an esophageal catheter. As the design depth of curvature becomes smaller, the effect of a constraint increases significantly. For a DR=0.0625, the increase in force from ER=1 to ER=0.1 is 56 to 1 compared to 7 to 1 for the previous example. This graph clearly illustrates that allowing a pull wire to move laterally away from the beam, i.e., higher ER values, also reduces the force needed to deflect the beam. This is particularly important in the presence of external constraints that resist lateral deflection and adds to the force the deflection mechanism must overcome to displace a body lumen.

While the unconstrained configuration for a deflection mechanism provides the lowest pull-wire force for deflection and is highly desirable to deflect a body lumen with external constraints, this is not always possible in clinical applications. Generally, there is insufficient internal space within a body lumen or catheter internal lumen to allow for such expansion of a pull wire away from the beam, especially when the deflection mechanism is longer or the required deflection larger. Using an esophageal-deflection application, a pull wire can only move at most 1 inch from the beam before it engages the wall of the esophagus. Having a pull wire engage the inner wall of a body lumen

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with any significant force is highly undesirable for many reasons. First, once the pull wire engages the vessel wall, the circularity of the vessel is distorted, becoming more elliptical and potentially undoing some benefits of deflection. Second, if unprotected, a pull wire could act as a knife cutting into the vessel wall causing tissue damage and/or possibly rupturing the vessel wall causing collateral damage to surrounding organs. To protect a vessel lumen from such damage but take advantage of the mechanical benefits of a pull wire moving away from the beam, it is desirable, in some embodiments, to have an expandable constraint around the deflection mechanism which limits the said displacement of a pull wire. The expandable constraint acts to allow a pull wire to move away from the beam until a limit is reached beyond which further lateral movement is restricted or impossible. Effectively the expandable constraint acts like a girdle limiting a pull wire to an ER value less than 1 but greater than that which occurs in steering catheter designs which typically have ER values in the range 0.1 or smaller.

Returning to an esophageal application, in some embodiments, it is desirable to limit the movement of a pull wire away from the beam to a maximum distance of 2.5 cm which is the diameter of an expanded esophagus. Since the maximum distance of a pull wire from the beam in some embodiments is 6.0 cm in an unconstrained configuration, the ER value, in some embodiments, is equal to or less than 0.42. This can be obtained by using a constraint which allows a pull wire to touch the wall of the esophagus. Comparatively, a deflection mechanism in which a lumen within the balloon catheter body acts as a constraint on pull wire movement, the ER value is approximately 0.08. In this example, the use of an expandable constraint which allows the pull wire to move away from the beam until it touches the esophageal wall gives an approximately five-fold reduction in pull wire force applied to deflect an esophagus, as illustrated in FIG. 7.

In summary, one goal of the present invention is to provide a deflection mechanism whereby a pull wire can expand laterally away from the beam during deflection. Another goal of the present invention is to provide a means to attain a certain distance between a pull wire and the beam which is greater than the diameter of the crossing profile of the catheter. Another goal of the present invention is to limit the lateral movement of a pull wire to a distance less than that attained by connecting the proximal and distal anchor points of a pull wire to form a chord of an arc created by the deflection. Another goal of the present invention is to provide a constraint around the deflection assembly which is expandable from a smaller diameter to a larger diameter. Another goal of the present invention is to provide a constraint which allows lateral movement of a pull wire to a certain expanded distance, after which increased lateral movement is significantly reduced or eliminated. Another goal of the present invention is to operably couple a catheter shaft containing one or more expandable elements with a deflection mechanism with expandable constraints. Another goal of the present invention is to reduce forces in a pull wire of the deflection assembly to more easily and safely deflect a body lumen in a clinical application. Another goal of the present invention is to provide a means whereby a deflected vessel is visible under fluoroscopy to determine the position of a body lumen with respect to critical structures, for example, an esophagus relative to the posterior wall of the left atrium.

FIG. 8A is a schematic diagram showing a deflection mechanism **800** with expandable constraints, according to



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one embodiment of the present invention. Deflection mechanism **800** is shown in a non-deflected or neutral state in FIG. **8A**. In some embodiments, deflection mechanism **800** includes a deflecting beam **802**. In some embodiments, pull wire **806** is attached to beam **802** on a distal end of beam **802** at joint **816**. In some embodiments, hypodermic tube **808** is attached to beam **802** on a proximal end of beam **802** at joint **812**. In some embodiments, a first shorter beam **810** is attached to deflecting beam **802** at its distal end by joint **814** so that pull wire **806** is positioned between beam **802** and first shorter beam **810** as shown in FIG. **8A**. In some embodiments, a second shorter beam **804** is attached to the proximal end of beam **802** at the juncture with the hypodermic tube **808** by joint **818** so that pull wire **806** is positioned between deflecting beam **802** and first and second shorter beams **810** and **804**.

FIG. **8B** is a schematic diagram of deflection mechanism **800** in a tensioned state, according to one embodiment of the present invention. In some embodiments, as pull wire **806** is tensioned, beam **802** curves in response to the shortening of the distance of the exposed pull wire **806** between points **814** and **812**. Tension in pull wire **806** causes wire **806** to straighten and form a chord to the arc defined by the fixed points **814** and **812** as shown in FIG. **8B**. However, as pull wire **806** moves away from beam **802**, it encounters first and second shorter beams **810** and **804** which resists the lateral movement of pull wire **806** away from deflecting beam **802**. In some embodiments, the effect of the resistance of the two smaller beams **810** and **804** is to modify the geometry of pull wire **806** so that it forms an arc with a larger radius curvature than that of beam **802** as shown in FIG. **8B**. The two smaller beams **810** and **804** act to limit expansion of pull wire **806**, i.e., constrain movement of pull wire **806** away from beam **802**. In some embodiments, the structural properties of the two smaller beams **810** and **804** are designed to change the geometric shape of pull wire **806** to prevent pull wire **806** from becoming a geometric chord of the deflected arc represented by beam **802**. In some embodiments, in the case where the constraining beams **810** and **804** are highly flexible, the shape of pull wire **806** will approach that of a chord of the beam arc, which allows the maximum possible movement of pull wire **806** away from the deflection beam **802**. In other embodiments, in the case where the constraining beams **810** and **804** are stiffer, the shape of pull wire **806** approaches that of beam **802** itself. Ultimately, in some embodiments, a stiffness will be reached at which the effect of constraining beams **810** and **804** is identical to that of a lumen of a catheter shaft into which a deflection mechanism has been placed, effectively negating the benefits of constraining beams **810** and **804**.

In one embodiment of the current invention for a device used for esophageal deflection, the deflecting beam **802** is made of one or more metals which have high yield strength and high hardness. In some embodiments, the yield strength is between 100,000 and 300,000 pounds per square inch (psi), in some embodiments, between 175,000 and 200,000 psi, in some embodiments, between 200,000 and 225,000 psi. In some embodiments, the metal hardness of deflecting beam **802** is between RC30 and RC60 (as used herein, the "RC" hardness refers to the Rockwell scale for hardness also known as "HRC"; see, e.g., [https://en.wikipedia.org/wiki/Rockwell\\_scale](https://en.wikipedia.org/wiki/Rockwell_scale)), in some embodiments, between RC45 and RC55, in some embodiments, between RC50 and RC55. In some embodiments, beam **802** material thickness ranges from 0.002 inches to 0.050 inches, in some embodiments, from 0.005 inches to 0.025 inches, in some embodiments, from 0.010 inches to 0.020 inches. In some embodiments,

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beam **802** widths range from 0.050 inches to 0.500 inches, in some embodiments, from 0.100 inches to 0.250 inches, in some embodiments, from 0.150 to 0.200 inches. In some embodiments, beam **802** lengths range from 3.0 inches to 20.0 inches, in some embodiments, from 5.0 inches to 10 inches, in some embodiments, from 6.0 inches to 9.0 inches.

In some embodiments, for other applications that deflect a body lumen where the deflecting forces are lower, beam **802** is made from plastic materials that typically have lower yield strengths and lower hardness. In some embodiments, plastic materials such as nylon, polyester and Teflon® are within the scope of the present invention for beam **802**.

In other embodiments of the present invention of a deflection mechanism with expandable constraints, the design of the constraint mechanism can be categorized as follows: namely, continuous, segmented or balloon-based. In some embodiments of a continuous design there is a single structural element surrounding beam **802** along its entire length, i.e., it extends to at least from its distal end to at least its proximal end (see, e.g., FIGS. **9A**, **10A**, **11A**, **12A**, and **17**). In some embodiments, the continuous structural element is expandable (see, e.g., FIGS. **9A**, **10A**, and **17**), a property which allows the constraint to change its diameter during beam deflection, or rigid (see, e.g., FIGS. **11A** and **12A**), a property which fixes the diameter of the constraint to a predetermined, fixed value. In some embodiments of a segmented design, selected constraining elements are affixed to beam **802** at various locations along beam **802** to constrain pull wire **806** at discrete locations along beam **802** (see, e.g., FIG. **8A**, FIG. **13A**, FIG. **14A**, and FIG. **15A**). In some embodiments, the segmented constraints are expandable (see, e.g., FIG. **14A**), which allows a change in physical size during deflection, or a fixed size (see, e.g., FIG. **15A**) similar to the continuous design. In some embodiments of a balloon-based design, the constraints are incorporated into a deflection catheter which contains the deflection mechanism, and in some such embodiments, the constraints are incorporated into the balloon(s) of a deflection catheter (see, e.g., FIG. **18**) or as an additional material affixed to the balloon(s) (see, e.g., FIG. **16**). Each of these designs will be discussed in more detail forthwith.

FIG. **9A** is a schematic diagram of a deflection assembly **900**, according to one embodiment of the present invention. In some embodiments, deflection assembly **900** includes a continuous elastic constraint. In this design, deflection assembly **900** is comprised of a deflection mechanism **905** which is surrounded by elastic tube **920** which can stretch radially as pull wire **806** moves laterally away from beam **802**.

FIG. **9B** is a cross-sectional view of deflection assembly **900** as viewed toward the right-hand side of FIG. **9A** from the middle of deflection assembly **900**, with beam **802** in its neutral or undeflected state, according to one embodiment of the present invention.

FIG. **9C** is a cross sectional view of deflection assembly **900** as viewed toward the right-hand side of FIG. **9A** from the middle of deflection assembly **900**, with beam **802** in its deflected state and pull wire **806** moved laterally away from beam **802**, according to one embodiment of the present invention. In some embodiments, the materials and tube wall thickness are selected to provide the desired distance of pull wire **806** from beam **802** at its maximum desired deflection. In some embodiments, constraint tubes **920** with thinner walls made of a lower-durometer material will allow more expansion of pull wire **806** away from beam **802** whereas



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tubes **920** with thicker walls made of higher-durometer materials will limit the expansion of pull wire **806** away from beam **802**.

In some embodiments of the present invention, tube **920** is made of silicone, polyurethane, latex or any plastic material which stretches easily when force is applied. In some embodiments, material durometers of tube **920** range from **10A** to **90A**, in some embodiments, from **20A** to **60A** and in some embodiments, from **40A** to **50A**. In some embodiments, material wall thicknesses of tube **920** range from 0.001 inches to 0.050 inches, in some embodiments, from 0.005 to 0.030 inches and in some embodiments, from 0.010 inches to 0.020 inches.

FIG. **10A** is a schematic diagram of a deflection assembly **1000**, according to one embodiment of the present invention. In some embodiments, deflection assembly **1000** includes a continuous elastic constraint. In some embodiments of this design, deflection assembly **1000** is comprised of deflection mechanism **1005** which is surrounded by wire mesh **1020** having a braided, woven or knitted material construction. In some embodiments, mesh **1020** is designed to expand to a fixed diameter beyond which expansion is no longer possible. In some embodiments of esophageal deflection, the maximum diameter of mesh **1020** is fixed at the largest esophageal diameter of approximately 2.5 cm. Depending on the structure of wire mesh **1020**, in some embodiments mesh **1020** foreshortens longitudinally as it expands radially as is the case with braiding. To accommodate this foreshortening, in some embodiments, mesh **1020** extends proximally along the body of the deflection mechanism, the extension length being determined as a multiple of the distance the mesh **1020** foreshortens at its maximum beam deflection. During deflection of beam **802**, the lateral movement of pull wire **806** expands mesh **1020** from its initially circular shape as shown in the cross-sectional view of FIG. **10B** to an ellipsoidal shape as shown in the cross-sectional view of FIG. **10C**, and at that point mesh **1020** has reached its maximum design diameter, mesh **1020** no longer expands, and thus the lateral movement of pull wire **806** away from beam **802** is constrained to this maximum value.

FIG. **11A** is a schematic diagram of a deflection assembly **1100**, according to one embodiment of the present invention. In some embodiments, deflection assembly **1100** includes a continuous constraint. In some embodiments of FIG. **11A**, deflection assembly **1100** is comprised of a deflection mechanism **1105** surrounded by a spring **1120** of a predetermined diameter that is attached to hypodermic tube **808** at joint **1115**. In some embodiments, spring **1120** is tightly wound such that adjacent coils touch each other, or loosely wound so that a space exists between each coil. The space between the coils can be a constant dimension along the entire length of the coil or can vary along its length. For example, in some embodiments it is advantageous to have a larger spacing in the center region of the beam to permit easier bending of beam **802** in that region. In some embodiments, the distal end of spring **1120** is such that the distal end of beam **802** is free to float inside the spring **1120**. For the spring **1120**, the ID (inner diameter) of spring **1120** is determined by the desired expansion ratio (ER) for a corresponding deflection catheter. In some embodiments, one consideration for the OD (outer diameter) of spring **1120** is that it must be smaller than the ID of a corresponding deflection catheter (e.g., a balloon catheter) in order to accommodate placement of deflection assembly **1100** therein.

In operation, in some embodiments, pull wire **806** is very close to beam **802** when beam **802** is in its straight configu-

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ration, as shown in FIG. **11B**. In some embodiments, as shown in FIG. **11C**, when beam **802** is deflected (and thus spring coil **1120** is deflected), pull wire **806** moves to the inside wall of spring coil **1120**, along the convex internal surface of spring coil **1120**, but the position of deflected beam **802** within spring coil **1120** as viewed in FIG. **11C** remains substantially unchanged from the position of the straight beam **802** within spring coil **1120** shown in FIG. **11B**.

FIG. **12A** is a schematic diagram of a deflection assembly **1200**, according to one embodiment of the present invention. In some embodiments, deflection assembly **1200** includes a continuous fixed constraint. This design is similar to that shown in FIG. **11A** with the exception that spring coil **1120** is replaced by a plastic tube **1220** with perpendicular cuts partially through its diameter, and plastic tube **1220** surrounds a deflection mechanism **1205**. In some embodiments of FIG. **12A**, deflection assembly **1200** is comprised of deflection mechanism **1205** which is surrounded by plastic tube **1220** which has been shaped into a cross sectional geometry of a letter "D" as shown in FIG. **12B**. In some embodiments, plastic tube **1220** contains cuts perpendicular to its longitudinal axis starting at the outer perimeter of the "D" and extending to but not penetrating through the inner edge **1224** of the "D" shape. As shown in FIG. **12D**, the resulting segments **1226** are separated by cuts **1228** and connected to the inner edge **1224** to form a continuous plastic structure, the bottom of which serves as a hinge connecting all sliced segments **1226** of the plastic tube **1220** to form a single entity.

In operation, in some embodiments, pull wire **806** will lie very close to beam **802** when beam **802** is in its neutral or straight configuration, as shown in FIG. **12B**. In some embodiments, as shown in FIG. **12C**, when beam **802** is deflected (and thus plastic tube **1220** is deflected), pull wire **806** moves to the inside surface of the flat part of the "D"-shape, but the position of deflected beam **802** within plastic tube **1220** as viewed in FIG. **12C** remains substantially unchanged from the position of the straight beam **802** within plastic tube **1220** shown in FIG. **12B**. The inside surface of the flat part of the "D" shape then acts as a constraint for pull wire **806** while the top of the "D"-segments expands in order to minimize the forces required to deflect the constraint tube **1220**.

Another set of embodiments of a deflection mechanism with expandable constraints according to the present invention can be classified as segmented designs in which constraining elements are affixed to beam **802** at selected locations along beam **802** to limit the movement of pull wire **806** at discrete locations along beam **802**. In some embodiments, the constraints are expandable; in other embodiments, the constraints have a fixed diameter in the same manner as those of a continuous constraint design.

FIG. **13A** is a schematic diagram of a deflection assembly **1300** in a neutral or undeflected state, according to one embodiment of the present invention. In some embodiments, deflection assembly **1300** includes a segmented expandable constraint. In some embodiments of deflection assembly **1300**, rings **1392** of circular material are placed over beam **802** and their position fixed to beam **802** by joint **1394** by using standard methods to join metals such as adhesives, spot welding, etc. In this concept, rings **1392** are similar to the continuous constraint designs discussed previously except that discrete rings **1392** of material are used at defined axial locations along deflection beam **802**. Similar to the choice of materials for a continuous constraint, rings **1392** of a segmented constraint can be elastic or rigid. In

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some embodiments, for an elastic constraint, rings **1392** are made of soft plastics with a tubular cross section similar to that shown in FIG. **13B**, which is similar to the cross section of a continuous constraint shown in FIG. **9A**. In some embodiments, when pull wire **806** is tensioned, the circular shape is deformed into an elongated structure allowing pull wire **206** to move away from beam **802**, as shown in FIG. **13C**, which is similar to FIG. **9C**. In operation, pull wire **806** now becomes a series of chords connected at each of the support points as shown in FIG. **13D**. Pull wire **806** forms chords between points **816** and **1396**, points **1396** and **1397**, **1897** and **1398**, and **1398** and the end of the support tube at point **1390**. This contrasts with the continuous arc formed by assembly **900** of FIG. **9A**, which uses a continuous elastic constrain.

Another embodiment of deflection assembly with an expandable constraint according to the present design is shown in FIGS. **14A-14C**. FIG. **14A** is a cross-sectional view of a deflection assembly **1401** with beam **802** in its neutral or undeflected state, according to one embodiment of the present invention. In some embodiments, segmented expandable constraints **1410** comprised of rings are made of spring wire shaped into multiple loops as shown in FIG. **14A**. In some embodiments, the wire loop **1410** is fastened to the underside of beam **802** with pull wire **806** passing through the inside of the loop.

FIG. **14B** is a cross-sectional view of deflection assembly **1401** with beam **802** in its deflected state and pull wire **806** moved laterally away from beam **802**, according to one embodiment of the present invention. In some embodiments, the wire loop **1410** is designed so that it can expand in diameter as pull wire **806** moves away from beam **802** and exerts a downward force on the loop **1410** opposite beam **802**. In some embodiments, the amount of expansion is controlled by the structural stiffness of the wire used to form the loop **1410** which is a function of its diameter and modulus of elasticity.

FIG. **14C** is a cross-sectional view of a deflection assembly **1402** with beam **802** in its deflected state and pull wire **806** moved laterally away from beam **802**, according to one embodiment of the present invention. In some embodiments, stops **1415** are placed on the ends of the wires of wire loop **1410** such that the wire loop **1410** can only expand until stops **1415** engage each other at the bottom of the loop as shown in FIG. **14C**.

FIG. **15A** is a cross-sectional view of a deflection assembly **1501** with beam **802** in its neutral or undeflected state, according to one embodiment of the present invention. In some embodiments, segmented fixed constraints comprised of rings **1510** are made of a rigid material similar to the materials used in a continuous constraint embodiment. In some embodiments, as shown in FIG. **15A** and FIG. **15B**, ring **1510** has a flat section at its interface with the top side of beam **802**. In some embodiments, ring **1510** is fastened to beam **802** using an adhesive or solder **1511** or other joining methods compatible with the metal composition of the materials involved. In some embodiments, in operation, the diameter of ring **1510** does not change between the neutral, non-deflected state of beam **802** (FIG. **15A**) to that of the deflected state beam **802** (FIG. **15B**). However, in the neutral state (FIG. **15A**), pull wire **806** resides in proximity to beam **802**, while in the deflected state (FIG. **15B**) pull wire **806** resides closer to the inside surface of ring **1510** opposite beam **802**. In some embodiments, the main advantage of this design is that segmentation allows the rigid elements to physically move relative to each other, reducing or elimi-

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nating the rigidity of the constraint material itself, thus not increasing the stiffness of the beam assembly.

FIG. **16** is a schematic diagram of a deflection assembly **1601**, according to one embodiment of the present invention. In some embodiments, deflection assembly **1601** incorporates segmented constraints into an elastic member **1630**, which encapsulates the deflection mechanism **1605**. In some embodiments, elastic member **1630** is part of an outer deflection catheter into which the deflection mechanism **1605** is inserted. In one embodiment, elastic member **1630** is a balloon which is inflated to expand the lumen into which deflection mechanism **1605** is placed. In some embodiments, elastic member **1630** has sections of increased wall thickness in certain axial segments along the length of the deflection mechanism. FIG. **16** shows elastic member **1630** as a balloon in which the thickened necks act as constraints. In some embodiments, this is accomplished by making the neck regions with a thicker material or adding another, separate layer of material **1624** to the outside of the balloon as shown in FIG. **16**. In some embodiments, ring material **1624** is elastic (in other embodiments, ring material **1624** is rigid). In some embodiments of the elastic design, the thickened band **1624** is incorporated into the balloon during the balloon blowing process, in which case the balloon is a single entity with varying wall thickness. In another embodiment, an elastic material **1624** is added over the balloon material once the multi-lobed balloon is mounted. In another embodiment, rings **1624** are made of a rigid material with one side of ring **1624** bonded to the balloons with an adhesive. In some embodiments, rigid bands **1624** are made of a radiopaque material that is visible during fluoroscopy, which is a useful property for determining the location of the deflected section of the catheter relative to other body structures such as the posterior wall of the heart during ablation for treatment of atrial fibrillation.

FIG. **17** is a schematic diagram of a deflection assembly **1700**, according to one embodiment of the present invention. In some embodiments, deflection assembly **1700** is suitable for deflecting a body lumen in a clinical setting and includes expandable constraints. In some embodiments, the distal end of deflection assembly **1700** is comprised of deflection mechanism **800**, illustrated in detail in FIG. **8**, and sheath **1720** which encapsulates the deflection mechanism **800** to seal the mechanism from fluid infiltration and to protect a body lumen from damage from elements of the deflection device. In some embodiments, sheath tubing **1720** is made from a thin-walled silicone tube of a diameter approximately that of shaft **1709**. In some embodiments, wall thicknesses of sheath **1720** range from 0.0005 inches to 0.050 inches, in some embodiments, from 0.003 inches to 0.015 inches, in some embodiments, from 0.005 inches to 0.010 inches, in some embodiments, approximately 0.005 inches. Alternatively, in some embodiments, sheath **1720** is made from a tube of a low-durometer material such as polyurethane, nylon, polyester, rubber latex or copolymers of these materials such as C-Flex®. In some embodiments, sheath **1720** is bonded to shaft **1709** at joint **1735** using an adhesive compatible with the materials of the shaft **808** and sheath tubing **1720**. Similarly, in some embodiments, at the distal end of the deflection device, tube **1725** is bonded to sheath **1720** with adhesive joint **1730** using an adhesive similar to that of joint **1735**. In some embodiments, the proximal end of deflection device **1700** includes a handle **1730** and sliding knob **1710** for tensioning/locking the position of the pull wire to deflect a body lumen during a procedure. In some embodiments, knob **1710** is slidably coupled to handle **1730**, and, in some embodiments, knob **1710** includes set screw

**1740** for the locking the position of the knob relative to the handle **1730** to fix the shape of the deflection mechanism once the desired degree of deflection is attained. In some embodiments, hypodermic tube **1708** interoperably couples pull wire **806** with knob **1710** so that any axial movement of the knob **1710** is translated into comparable movement of pull wire **806** for purposes of changing the degree of lateral movement of the deflection mechanism.

In one embodiment, a deflection device which contains a deflection mechanism with expandable constraint such as deflection assembly **1700** is used to deflect an esophagus in a cardiac ablation procedure for treatment of atrial fibrillation. In this procedure, deflection device **1700** is placed in the mouth of the patient and the distal end of the device passed through the throat into the esophagus and positioned at the desired location within the esophagus. Once positioned, the slide knob **1710** is moved axially to curve the deflection device, thereby translating the esophagus consistent with the curvature of the deflection mechanism. If the location of the deflection is not oriented with respect to thoracic cavity or relevant cardiac structures as desired, the deflection mechanism is returned to its neutral state, the deflection device rotated in the esophagus to the desired orientation and the deflection mechanism curved using the slide knob on the handle. Once the desired orientation and degree of curvature are obtained, the position of the knob **1710** on the handle **1730** is locked using set screw **1740** and a cardiac ablation procedure is performed. Upon completion of the procedure, the knob **1710** on the handle **1730** is released, the deflection device returned to its neutral position and the deflection device retracted from the esophagus.

FIG. **18** is a schematic diagram of a deflection assembly **1800**, according to one embodiment of the present invention. In some embodiments, deflection assembly **1800** is for use in a clinical setting and uses a deflection mechanism with expandable constraints. In some embodiments, deflection assembly **1800** is comprised of deflection mechanism **800**, illustrated in detail in FIG. **8**, which is surrounded by balloon catheter **1805**. In some embodiments, balloon catheter **1805** includes balloon **1820**, which encapsulates deflection mechanism **800**, catheter shaft **1860**, which is operably coupled to balloon **1820**, and handle **1830**, which operably couples to deflection mechanism **800** and balloon **1820**. In some embodiments, balloon **1820** is made of a thin sheet of **90A** durometer polyurethane. In some embodiments, wall thicknesses of balloon **1820** range from 0.0005 inches to 0.050 inches, in some embodiments, from 0.001 inches to 0.015 inches, in some embodiments, from 0.001 inches to 0.005 inches, and in some embodiments, approximately 0.0025 inches. In some embodiments, a sheet of polyurethane is formed into balloon **1820** with a cylindrical section **1821** at its center, with cones **1822** and **1824** on each end that taper to form necks **1826** and **1828**, which interface with the shaft **1860** of balloon catheter **1805**. In some embodiments, the diameter of the cylindrical part **1821** of the balloon **1820** is selected as the desired diameter of the inflated balloon **1820** in a clinical setting. In some embodiments, the diameter ranges from 0.125 inches to 1.5 inches or in some embodiments, from 0.375 to 1.0 inches or in some embodiments, between 0.65 and 0.75 inches when inflated. Alternatively, in some embodiments, balloon **1820** is made from an extruded tube of a desired material and the tube heated and blown into a mold with the desired balloon shape. In some embodiments, other durometer polyurethane materials are used ranging from **10** Shore A thru **95** Shore A and from **50** Shore D to **70** Shore D. Alternatively, in some embodiments, more-compliant balloons **1820** are designed with a

lower- or softer-durometer material such as in the range **10** Shore A to **30** Shore A which allows the balloon diameter to be changed at the time of a procedure by increasing fluid pressure within the balloon. Alternatively, in some embodiments, non-compliant balloons **1820** are designed using materials in the range **30** to **70** Shore D, the use of which implies the diameter cannot be changed during a clinical procedure. The use of **90** Shore A as the base material gives the balloon **1820** a semi-compliant characteristic, which means that the diameter can be changed during a procedure if sufficient pressure is applied to cause stretching of the balloon material. Alternatively, in some embodiments, balloon **1820** is made from other materials which have the desired range of durometers, such as silicone, latex rubber, nylon, polyester or copolymers of these materials such as C-Flex®. In some embodiments, balloon **1820** is bonded to catheter shaft **1860** using neck joint **1832** with an adhesive compatible with the materials of the shaft and balloon. Similarly, in some embodiments, at the distal end of balloon catheter **1805**, tube **1845** is bonded to neck **1828** with adhesive joint **1834** using an adhesive similar to that of joint **1832**. In some embodiments, the proximal end of balloon catheter **1805** includes a handle **1830**, sliding knob **1810** for tensioning/locking the pull wire and a port for inflation/deflation of the balloon similar to that of the deflection device shown in FIG. **17** (e.g., in some embodiments, knob **1810** includes set screw **1840** for the locking the position of the knob **1810** relative to the handle **1830** to fix the shape of the deflection mechanism once the desired degree of deflection is attained). Additionally, in some embodiments, tube **1865** is attached to handle **1830** and is operably coupled to balloon **1820** for purposes of inflating and deflating the balloon **1820**.

In some embodiments, deflection assembly **1800** is used to deflect an esophagus in a cardiac-ablation procedure for treatment of atrial fibrillation. In some embodiments of this procedure, a vacuum is pulled on the inside of the deflection assembly **1800** using a syringe and side port **1865** with Luer, after which balloon **1820** is wrapped tightly around the deflection mechanism **800**. In some embodiments, the deflection assembly **1800** is placed in the mouth of the patient and the distal end of the device passed through the throat and into the esophagus and positioned at the desired location in the esophagus. The balloon **1820** is then inflated with a fixed volume of a saline/contrast agent to expand the esophagus to a larger diameter in order to tighten the esophagus for purposes of visualization and ease of displacement. Once positioned, the knob **1810** on the handle **1830** is used to curve the deflection device which translates the esophagus in the same direction as the curvature of the deflection mechanism **800**. If the plane of deflection is not oriented correctly with respect to the thoracic cavity or relevant cardiac structures, the deflection mechanism **800** is returned to its neutral state, the deflection device is then rotated to the desired position within the inflated balloon **1820** and the deflection mechanism **800** curved once again using the slide knob **1810** on the handle **1830**. Once the desired orientation and degree of curvature is obtained, the position on the knob **1810** on the handle **1830** is locked and a cardiac ablation procedure performed. After completion of a procedure, the knob **1810** on the handle **1830** is unlocked, the deflection mechanism **800** within the balloon catheter **1805** returned to its neutral position, the balloon **1820** deflated by extracting fluid from the balloon and the balloon catheter **1805** retracted from the esophagus.

In some embodiments, the present invention provides a deflection system for deflecting a body lumen that includes



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a deflection mechanism, wherein the deflection mechanism includes: a beam having a proximal end and a distal end, wherein the beam includes a neutral position and a deflected position, a pull wire coupled to the distal end of the beam, wherein the beam is configured to be placed in the deflected position when a tension force is applied to the pull wire, and wherein at least a portion of the pull wire is configured to move to a displacement distance away from the beam when the tension force is applied to the pull wire, and one or more constraint members operatively coupled to the beam, wherein each one of the one or more constraint members is configured to limit the displacement distance of the pull wire from the beam when the tension force is applied to the pull wire.

In some embodiments of the system, the deflection mechanism further includes: a tubular support member coupled to the proximal end of the beam, wherein the pull wire is configured to pass through the tubular support member; and a handle coupled to the tubular support member, wherein the handle includes a tension mechanism configured to provide the tension force to the pull wire in order to place the beam in the deflected position.

In some embodiments, the system further includes a deflection catheter that includes: a catheter shaft that includes an internal lumen, a balloon affixed to the catheter shaft, and a hub affixed to the internal lumen of the catheter shaft, wherein at least a portion of the deflection mechanism is configured to be placed in the internal lumen of the catheter shaft.

In some embodiments of the system, each one of the one or more constraint members is configured to limit the displacement distance to a value such that the pull wire is prevented from forming a geometric chord of the beam when the beam is in the deflected position. In some embodiments, each one of the one or more constraint members is configured to limit the displacement distance to a value such that the pull wire forms an arc with a larger radius of curvature than that of the beam. In some embodiments, the deflection mechanism provides an expansion ratio (ER) that is in a range from about 0.15 to about 0.4.

In some embodiments of the system, the one or more constraint members includes a plurality of mini-beams including a first mini-beam operatively coupled to the beam at the distal end of the beam and a second mini-beam operatively coupled to the beam at the proximal end of the beam, wherein each one of the plurality of mini-beams is shorter than the beam. In some embodiments, the one or more constraint members includes an elastic tube that surrounds the beam and the pull wire, wherein the elastic tube is configured to stretch radially as the pull wire moves to the displacement distance away from the beam. In some embodiments, the one or more constraint members includes a plastic tube that surrounds the beam and the pull wire, wherein a cross-sectional geometry of the plastic tube includes an inner section and a curved segmented outer section, wherein the curved segmented outer section includes a plurality of segments that are separated from each other radially along the curved segmented outer section.

In some embodiments of the system, the one or more constraint members includes a plurality of rings including a first ring and a second ring, wherein each one of the plurality of rings surrounds the beam and the pull wire, wherein each one of the plurality of rings is configured to stretch radially as the pull wire moves to the displacement distance away from the beam, and wherein the first ring is located at a first axial location along the beam and the second ring is located at a second axial location along the beam.

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In some embodiments of the system, the one or more constraint members include a wire mesh that surrounds the beam and the pull wire. In some embodiments, the one or more constraint members include a spring that surrounds the beam and the pull wire. In some embodiments, the one or more constraint members include a plurality of elastic members that surrounds the beam and the pull wire, wherein each respective elastic member of the plurality of elastic members includes a first wall thickness and a second wall thickness, wherein the second wall thickness of each respective elastic member is located at one or more selective axial positions of the elastic member, and wherein the second wall thickness is greater than the first wall thickness.

In some embodiments of the system, the one or more constraint members include a plurality of mini-beams including a first mini-beam operatively coupled to the beam at the distal end of the beam and a second mini-beam operatively coupled to the beam at the proximal end of the beam, wherein each one of the plurality of mini-beams is shorter than the beam, the deflection system further including a sheath configured to encapsulate the deflection mechanism in order to seal the deflection mechanism from fluid infiltration.

In some embodiments of the system, the one or more constraint members include a plurality of mini-beams including a first mini-beam operatively coupled to the beam at the distal end of the beam and a second mini-beam operatively coupled to the beam at the proximal end of the beam, wherein each one of the plurality of mini-beams is shorter than the beam, the deflection system further including a balloon catheter configured to surround the deflection mechanism.

In some embodiments of the system, the beam has a cross-sectional-width dimension and a cross-sectional-height dimension, wherein the cross-sectional-width dimension is larger than the cross-sectional-height dimension. In some such embodiments, the beam further includes a length dimension and the beam is configured to preferentially bend along the length dimension. In some embodiments, the beam has a rectangular cross section. In some embodiments, the beam has a square-shaped cross section. In some embodiments, the beam has an oval-shaped cross section. In some embodiments, the beam has a circular cross section. In some embodiments, the beam has a circular cross section that has been flattened by compression. In some embodiments, the beam includes a bi-metal strip having a first metal and a second metal, wherein the bi-metal strip is configured to bend upon application of an applied current, and wherein the applied current causes the first metal to heat at a first heat rate and the second metal to heat at a second heat rate that is different from the first heat rate. In some embodiments, the beam includes a bi-metal strip having a first metal and a second metal, wherein the bi-metal strip bends upon application of an applied current, wherein the applied current causes at least one of the first metal and the second metal to undergo a phase change.

In some embodiments, the present invention provides a deflection mechanism that includes a beam; a pull wire connected to the beam on a first end of the beam; a tubular support column connected to the beam on a second end of the beam, wherein the pull wire passes through the tubular support column; a handle connected to the support column containing a mechanism for tensioning the pull wire; and one or more constraints attached to the beam which change shape during tensioning of a pull wire to allow the pull wire to be displaced laterally from the beam during deflection but

which limit the displacement do a distance less than that formed in the absence of a constraint.

In some embodiments, the present invention provides a deflection catheter that includes a balloon affixed to a catheter shaft with an internal lumen to which is affixed a hub, the internal lumen containing a deflection mechanism that includes: a beam; a pull wire connected to the beam on a first end of the beam; a tubular support column connected to the beam on a second end of the beam, wherein the pull wire passes through the tubular support column; a handle connected to the support column containing a mechanism for tensioning the pull wire; and one or more constraints attached to the beam which change shape during tensioning of a pull wire to allow the pull wire to be displaced laterally from the beam during deflection but which limit the displacement do a distance less than that formed in the absence of a constraint.

In some embodiments, the present invention provides a method for deflecting a body lumen that includes providing a deflection mechanism, wherein the deflection mechanism includes: a beam having a proximal end and a distal end, wherein the beam includes a neutral position and a deflected position, a pull wire, and one or more constraint members; the method further including coupling the pull wire to the distal end of the beam; operatively coupling the one or more constraint members to the beam; applying a tension force to the pull wire such that the beam is placed in the deflected position, wherein at least a portion of the pull wire moves to a displacement distance away from the beam during the applying of the tension force; and limiting the displacement distance of the pull wire from the beam via the one or more constraint members.

In some embodiments of the method, the limiting of the displacement distance of the pull wire includes preventing the pull wire from forming a geometric chord of the beam when the beam is in the deflected position. In some embodiments, the beam has a first radius of curvature in the deflected position, wherein the limiting of the displacement distance of the pull wire includes limiting the displacement distance to a value such that the pull wire forms an arc having a second radius of curvature, and wherein the second radius of curvature is larger than the first radius of curvature.

In some embodiments, the method further includes providing a deflection catheter that includes: a catheter shaft that includes an internal lumen, a balloon affixed to the catheter shaft, and a hub affixed to the internal lumen of the catheter shaft; the method further including placing at least a portion of the deflection mechanism in the internal lumen of the catheter shaft.

In some embodiments of the method, the one or more constraint members further include a plurality of mini-beams, wherein the plurality of mini-beams includes a first mini-beam and a second mini-beam, wherein each one of the plurality of mini-beams is shorter than the beam, the method further including: operatively coupling the first mini-beam to the beam at the distal end of the beam; and operatively coupling the second mini-beam to the beam at the proximal end of the beam.

In some embodiments of the method, the one or more constraint members further include an elastic tube, the method further including surrounding the beam and the pull wire with the elastic tube, wherein the elastic tube is configured to stretch radially as the pull wire moves to the displacement distance away from the beam.

In some embodiments of the method, the one or more constraint members include a plurality of rings including a first ring and a second ring, wherein each one of the plurality

of rings is configured to stretch radially as the pull wire moves to the displacement distance away from the beam, the method further including: placing the first ring around the beam at a first axial location along the beam; and placing the second ring around the beam at a second axial location along the beam.

In some embodiments of the method, the one or more constraint members further include a plurality of mini-beams, wherein the plurality of mini-beams includes a first mini-beam and a second mini-beam, wherein each one of the plurality of mini-beams is shorter than the beam, the method further including: operatively coupling the first mini-beam to the beam at the distal end of the beam; operatively coupling the second mini-beam to the beam at the proximal end of the beam; providing a sheath; and encapsulating the deflection mechanism with the sheath in order to seal the deflection mechanism from fluid infiltration.

In some embodiments of the method, the one or more constraint members further include a plurality of mini-beams, wherein the plurality of mini-beams includes a first mini-beam and a second mini-beam, wherein each one of the plurality of mini-beams is shorter than the beam, the method further including: operatively coupling the first mini-beam to the beam at the distal end of the beam; operatively coupling the second mini-beam to the beam at the proximal end of the beam; providing a balloon catheter; and inserting the deflection mechanism into the balloon catheter.

In some embodiments, the present invention provides a system for deflecting a body lumen that includes a deflection mechanism, wherein the deflection mechanism includes: a beam having a proximal end and a distal end, wherein the beam includes a neutral position and a deflected position, and a pull wire; the system further including: means for coupling the pull wire to the distal end of the beam; and means for applying a tension force to the pull wire such that the beam is placed in the deflected position, wherein at least a portion of the pull wire moves to a displacement distance away from the beam during the applying of the tension force, and wherein the deflection mechanism further includes means for limiting the displacement distance of the pull wire from the beam.

It is specifically contemplated that the present invention includes embodiments having combinations and subcombinations of the various embodiments and features that are individually described herein (i.e., rather than listing every combinatorial of the elements, this specification includes descriptions of representative embodiments and contemplates embodiments that include some of the features from one embodiment combined with some of the features of another embodiment). Further, some embodiments include fewer than all the components described as part of any one of the embodiments described herein. Still further, it is specifically contemplated that the present invention includes embodiments having combinations and subcombinations of the various embodiments described herein and the various embodiments described by the related applications and publications incorporated by reference in paragraphs above of the present application.

It is to be understood that the above description is intended to be illustrative, and not restrictive. Although numerous characteristics and advantages of various embodiments as described herein have been set forth in the foregoing description, together with details of the structure and function of various embodiments, many other embodiments and changes to details will be apparent to those of skill in the art upon reviewing the above description. The scope of the invention should be, therefore, determined with reference to

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the appended claims, along with the full scope of equivalents to which such claims are entitled. In the appended claims, the terms “including” and “in which” are used as the plain-English equivalents of the respective terms “comprising” and “wherein,” respectively. Moreover, the terms “first,” “second,” and “third,” etc., are used merely as labels, and are not intended to impose numerical requirements on their objects.

What is claimed is:

1. A deflection system for deflecting a body lumen comprising:

a deflection mechanism, wherein the deflection mechanism includes:

a beam having a proximal end and a distal end, wherein the beam includes a neutral position and a curved-beam deflected position, wherein the beam is configured such that, in the deflected position, the beam is curved to a curved arc having a first radius of curvature,

a pull wire coupled to the distal end of the beam, wherein the beam is configured to be curved to the deflected position when a tension force is applied to the pull wire, and wherein at least a portion of the pull wire is configured to move to a displacement distance away from the beam when the tension force is applied to the pull wire, and

one or more constraint members operatively coupled to the beam, wherein each one of the one or more constraint members is configured to limit the displacement distance of the pull wire from the curved beam when the tension force is applied to the pull wire, wherein the one or more constraint members include a plurality of mini-beams, wherein the plurality of mini-beams includes a first mini-beam distally coupled to the beam and a second mini-beam proximally coupled to the beam, wherein each one of the plurality of mini-beams is shorter than the beam, and wherein the pull wire is located between the beam and each respective one of the plurality of mini-beams.

2. The deflection system of claim 1, wherein the deflection mechanism further includes:

a tubular support member coupled to the proximal end of the beam, wherein the pull wire is configured to pass through the tubular support member; and

a handle coupled to the tubular support member, wherein the handle includes a tension mechanism configured to provide the tension force to the pull wire in order to place the beam in the deflected position.

3. The deflection system of claim 1, further comprising: a deflection catheter that includes:

a catheter shaft that includes an internal lumen, a balloon affixed to the catheter shaft, and a hub affixed to the internal lumen of the catheter shaft,

wherein at least a portion of the deflection mechanism is configured to be placed in the internal lumen of the catheter shaft.

4. The deflection system of claim 1, wherein the deflection mechanism provides an expansion ratio (ER) that is in a range from about 0.15 to about 0.4.

5. The deflection system of claim 1, wherein the one or more constraint members also include an elastic tube that surrounds the beam and the pull wire, wherein the elastic tube is configured to stretch radially as the pull wire moves to the displacement distance away from the beam.

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6. The deflection system of claim 1, wherein the one or more constraint members also include a plastic tube that surrounds the beam and the pull wire, wherein a cross-sectional geometry of the plastic tube includes an inner section and a curved segmented outer section, wherein the curved segmented outer section includes a plurality of segments that are separated from each other radially along the curved segmented outer section.

7. The deflection system of claim 1, wherein the one or more constraint members also include a plurality of rings including a first ring and a second ring, wherein each one of the plurality of rings surrounds the beam and the pull wire, wherein each one of the plurality of rings is configured to stretch radially as the pull wire moves to the displacement distance away from the beam, and wherein the first ring is located at a first axial location along the beam and the second ring is located at a second axial location along the beam.

8. The deflection system of claim 1, wherein the one or more constraint members also include a plurality of elastic members that surrounds the beam and the pull wire, wherein each respective elastic member of the plurality of elastic members includes a first wall thickness and a second wall thickness, wherein the second wall thickness of each respective elastic member is located at one or more selective axial positions of the elastic member, and wherein the second wall thickness is greater than the first wall thickness.

9. The deflection system of claim 1, further comprising: a sheath configured to encapsulate the deflection mechanism in order to seal the deflection mechanism from fluid infiltration.

10. The deflection system of claim 1, further comprising: a balloon catheter configured to surround the deflection mechanism.

11. The deflection system of claim 1, wherein the beam has a cross-sectional-width dimension and a cross-sectional-height dimension, and wherein the cross-sectional-width dimension is larger than the cross-sectional-height dimension.

12. A method for deflecting a body lumen comprising: providing a deflection mechanism, wherein the deflection mechanism includes:

a beam having a proximal end and a distal end, wherein the beam includes a neutral position and a deflected position, wherein the beam includes a first radius of curvature in the deflected position,

a pull wire, and

one or more constraint members, wherein the one or more constraint members include a plurality of mini-beams, wherein the plurality of mini-beams includes a first mini-beam and a second mini-beam, wherein each one of the plurality of mini-beams is shorter than the beam;

operatively coupling the first mini-beam to the beam distally;

operatively coupling the second mini-beam to the beam proximally;

locating the pull wire between the beam and the plurality of mini-beams;

coupling the pull wire to the distal end of the beam; applying a tension,

force to the pull wire such that the beam is placed in the deflected position, wherein at least a portion of the pull wire moves to a displacement distance away from the beam during the applying of the tension force; and limiting the displacement distance of the pull wire from the beam via the one or more constraint members.

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13. The method of claim 12, wherein the limiting of the displacement distance of the pull wire includes preventing the pull wire from forming a geometric chord of the beam when the beam is in the deflected position.

14. The method of claim 12, wherein the limiting of the displacement distance of the pull wire includes limiting the displacement distance to a value such that the pull wire forms an arc having a second radius of curvature, and wherein the second radius of curvature is larger than the first radius of curvature.

15. The method of claim 12, wherein the one or more constraint members further include an elastic tube, the method further comprising:

surrounding the beam and the pull wire with the elastic tube, wherein the elastic tube is configured to stretch radially as the pull wire moves to the displacement distance away from the beam.

16. The method of claim 12, wherein the one or more constraint members include a plurality of rings including a first ring and a second ring, wherein each one of the plurality of rings is configured to stretch radially as the pull wire moves to the displacement distance away from the beam, the method further comprising:

placing the first ring around the beam at a first axial location along the beam; and

placing the second ring around the beam at a second axial location along the beam.

17. The method of claim 12, further comprising:

providing a sheath; and

encapsulating the deflection mechanism with the sheath in order to seal the deflection mechanism from fluid infiltration.

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18. A system for deflecting a body lumen comprising:  
a deflection mechanism, wherein the deflection mechanism includes:

a beam having a proximal end and a distal end, wherein the beam includes a neutral position and a curved-beam deflected position, and wherein the beam includes a first radius of curvature in the curved-beam deflected position, and

a pull wire;

means for coupling the pull wire to the distal end of the beam; and

means for applying a tension force to the pull wire such that the beam is placed in the deflected position, wherein at least a portion of the pull wire moves to a displacement distance away from the beam during the applying of the tension force, and wherein the deflection mechanism further includes:

means for limiting the displacement distance of the pull wire from the beam wherein the means for limiting the displacement distance of the pull wire includes a plurality of mini-beams, wherein the plurality of mini-beams includes a first mini-beam operatively coupled to the beam at the distal end of the beam and a second mini-beam operatively coupled to the beam at the proximal end of the beam, wherein each one of the plurality of mini-beams is shorter than the beam, and wherein the pull wire is located between the beam and the plurality of mini-beams.

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